

Power Electronics

- (i) SCR
- (ii) Phase uncontrolled rectifiers
- (iii) Inverters
- (iv) Choppers.

Power electronics ?

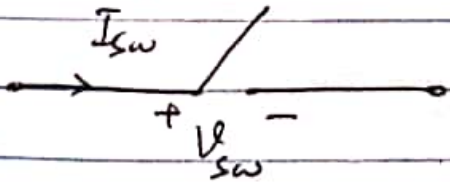
- (i) controls the flow of power in a circuit.
- (ii) conditioning of power.

To control \rightarrow switches \rightarrow power semiconductor devices.
Why control ?

To finish mismatch b/w supply and load.
eg AC supply \rightarrow DC load.
 \rightarrow power electronics.

Switches

The difference between electrical and P.E circuits is only that of switches.

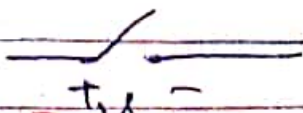


(i) Ideal case.

(a) When switch is closed $V_{sw} = 0V$
 $I_{sw} = \text{anything.}$

$$\text{Power loss} = V_{sw} I_{sw} = 0W$$

(b) when switch is open.



$V_{sw} = \text{anything}$
 $I_{sw} = 0A$

Data: / /

$$\Rightarrow P_{sw} = 0 W$$

(c) Ideally, the time taken by a switch to turn ON or turn OFF is zero.

t_{ON} \rightarrow time taken to turn ON the switch

t_{OFF} \rightarrow " " turn OFF " "

ON \rightarrow steady state ON OFF \rightarrow steady state OFF.
 \rightarrow the voltage or current has reached its final value.

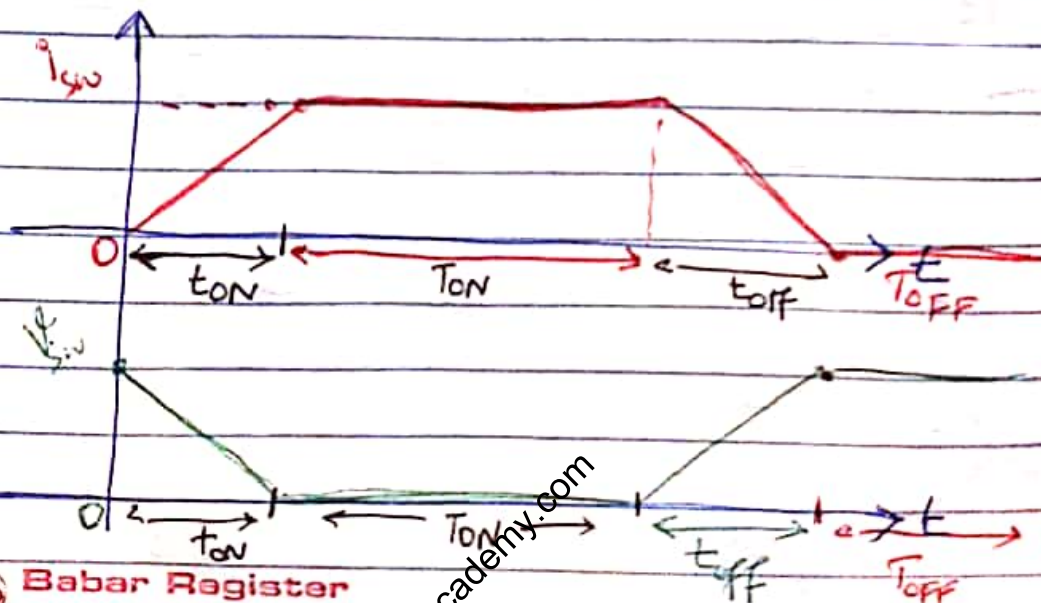
$$OFF \rightarrow ON = t_{ON}$$

$$ON \rightarrow OFF = t_{OFF}$$

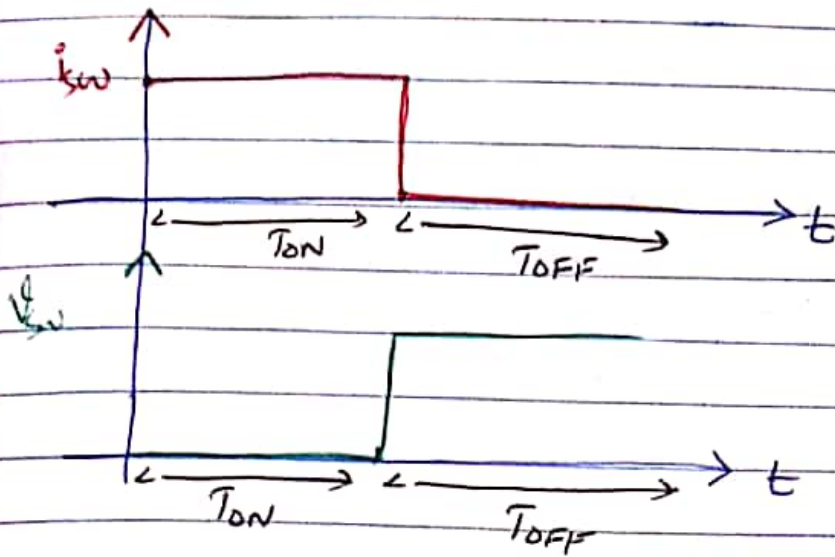
T_{ON} \rightarrow The time during which the switch is under steady state ON condition.

T_{OFF} \rightarrow time " " steady state OFF "

For ideal switch $\left\{ \begin{array}{l} t_{ON} = 0 \text{ sec} \\ t_{OFF} = 0 \text{ sec} \end{array} \right.$



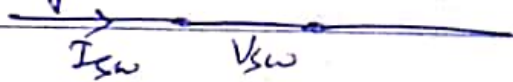
For ideal switch;



(ii) Practical case

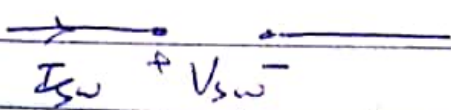
(a) ON state

practically there will be some drop across v_{sw} .



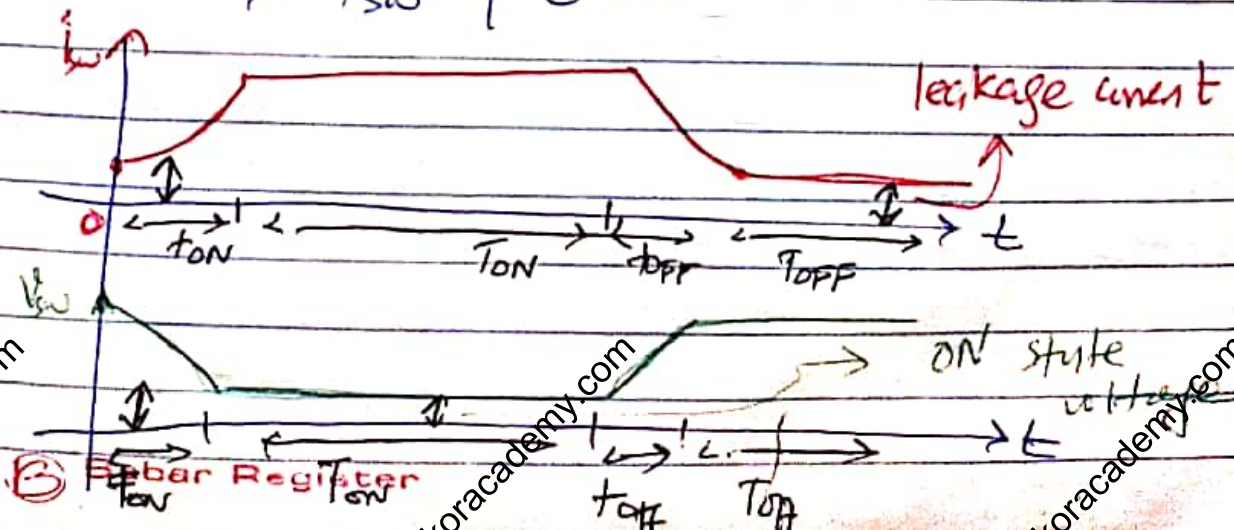
$$\Rightarrow P = v_{sw} \cdot I_{sw} \neq 0 \text{ W}$$

(b) OFF state



Here $I_{sw} \neq 0$
 \hookrightarrow leakage current

$$\Rightarrow P_{sw} \neq 0 \text{ W}$$



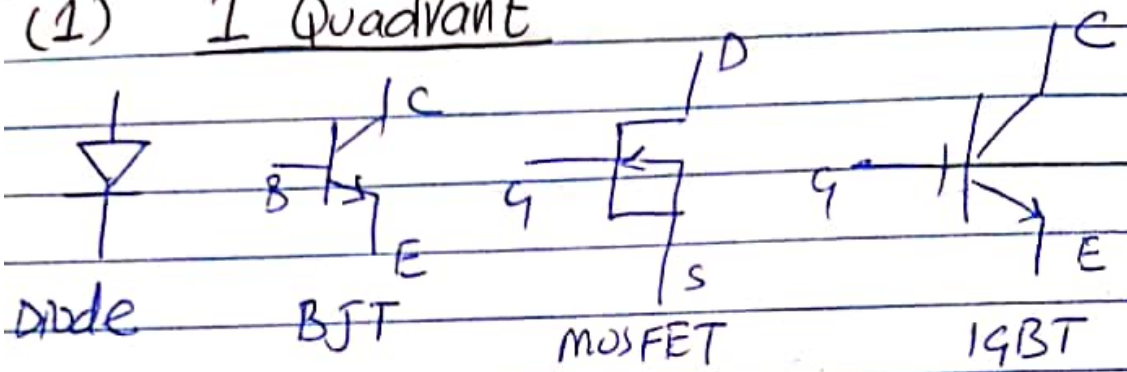
Bar Register

Quadrant Operation of Switches

1 quadrant, 2 quadrant, 4 quadrant
No 3 quadrant.

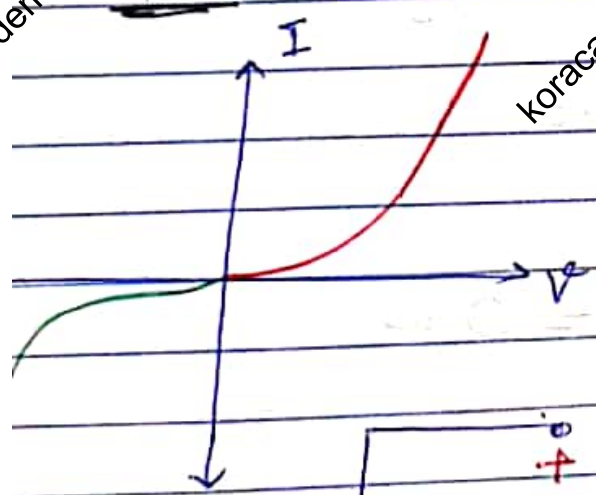
The characteristics are I_{sw} vs V_{sw}

(1) 1 Quadrant



Diode

Current controlled



Current flows from anode to cathode \rightarrow diode is ON.

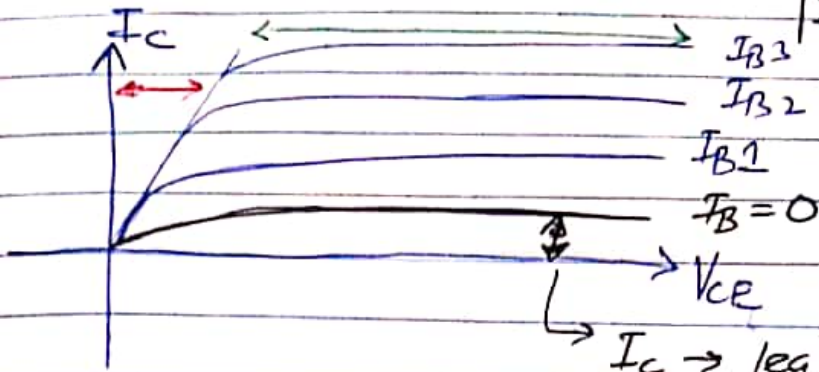
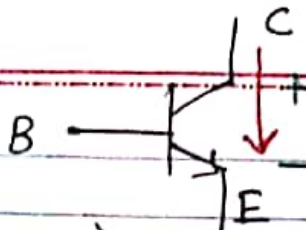
\rightarrow anode = +ve cathode = -ve
Current flows from cathode to anode \rightarrow diode is OFF.



So this is a 1 quadrant operation (2nd Q) which means \rightarrow diode is a unidirectional current flow device \rightarrow ON

\rightarrow diode is a unipolar device.] OFF
blocks negative voltage

BJT voltage controlled



saturation region.

Active/amplification region
↳ amplifiers

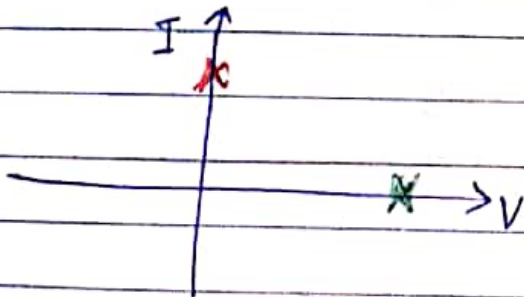
↳ ON switch

↳ $V_{CE} \downarrow I_C \uparrow$

cut off region
↓
OFF switch

↳ $V_{CE} \uparrow I_C \downarrow$

BJT → +ve I flows → I_C → ON
↳ blocks +ve voltage → V_{CE} → OFF

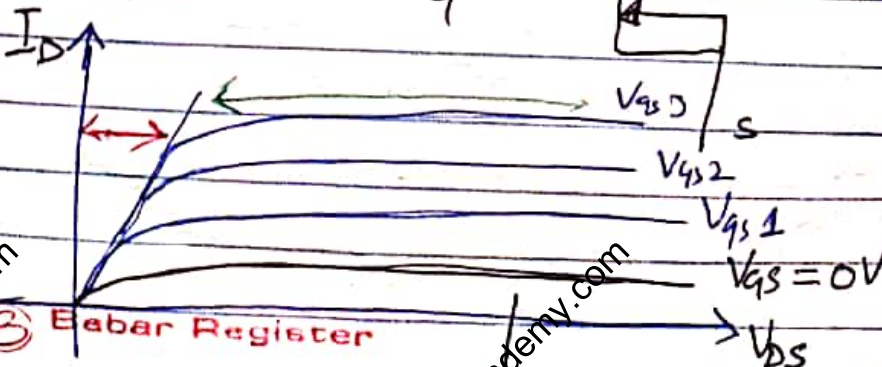
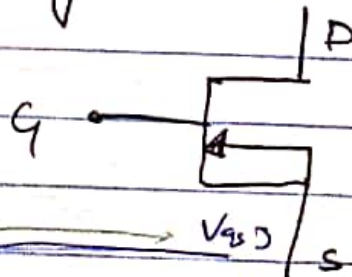


Single quadrant

BJT → unidirectional current
unipolar device

BJT is called bipolar in sense of majority and minority carriers.

FET



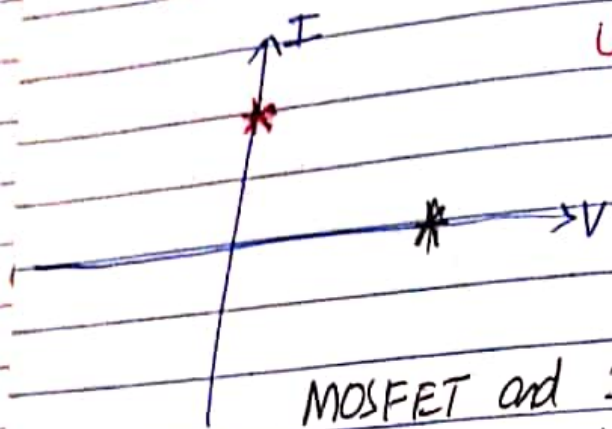
Saturation
Active

↳ cut off region

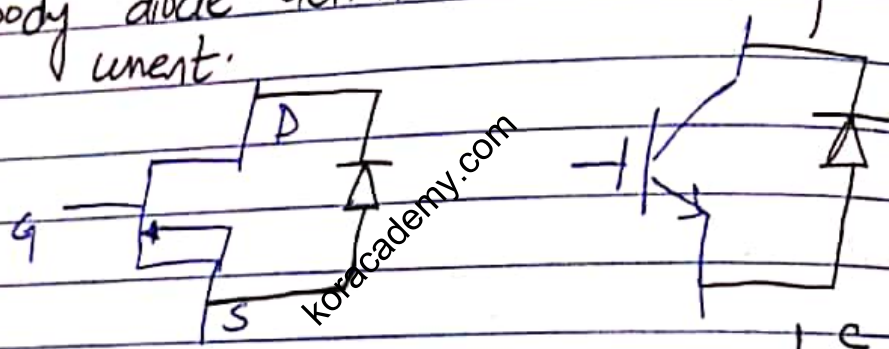
ON \rightarrow saturation
current flows from
D to S

OFF \rightarrow cut off
voltage appears across
D and S

unidirectional current flow
Unipolar device

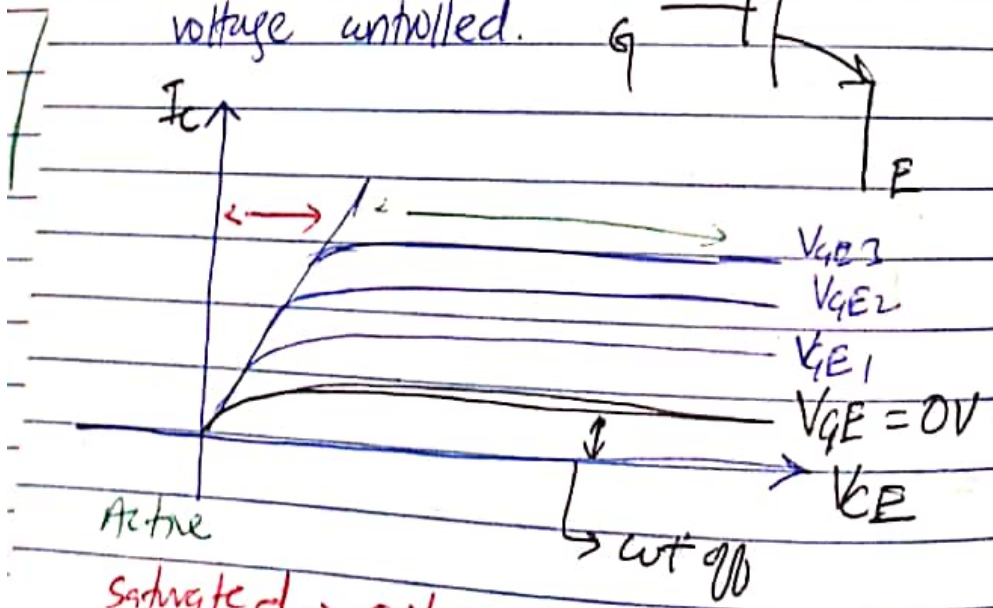
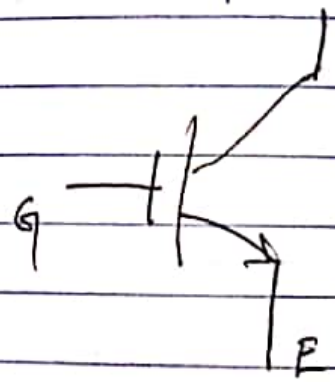


MOSFET and IGBT have internal
body diode action \rightarrow bidirectional flow of
current.



IGBT

voltage controlled.

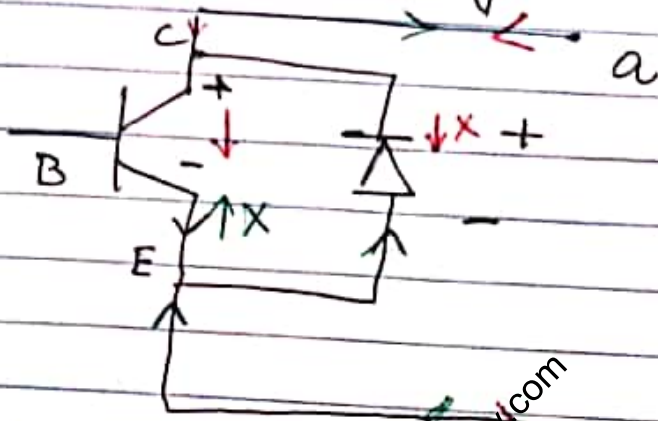


saturated \rightarrow ON \rightarrow I_c flows \rightarrow ideally $V_{CE} = 0$
OFF \rightarrow $I_c = 0$, blocking voltage = $+V_{CE}$



unidirectional current flow in
unipolar switch.

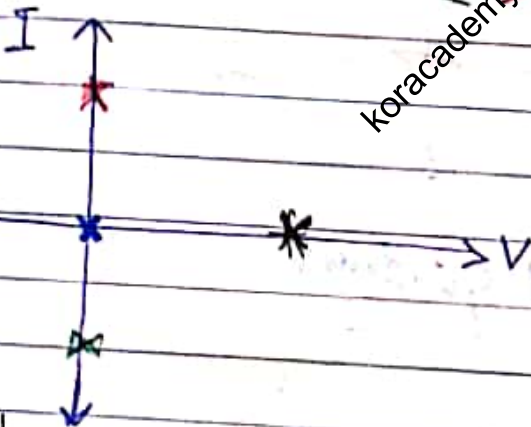
Consider the following.



Composite
switch

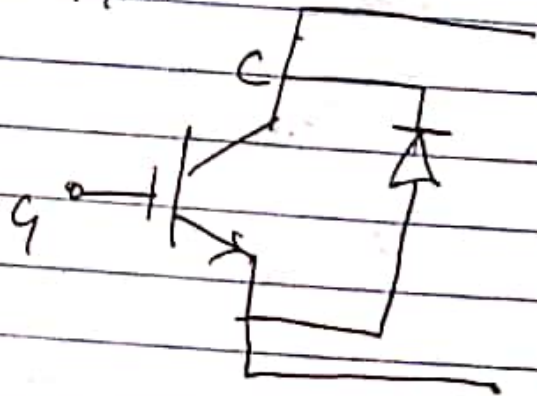
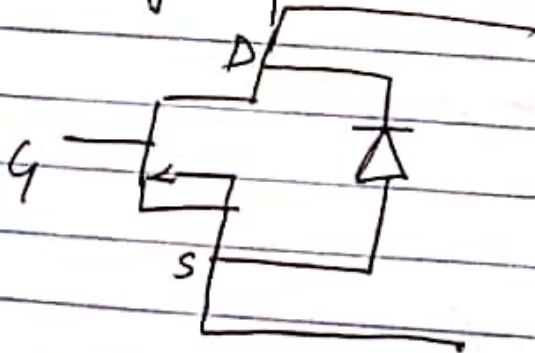
ON \rightarrow voltage = 0
2 quadrant switch

Bidirectional
current flow.



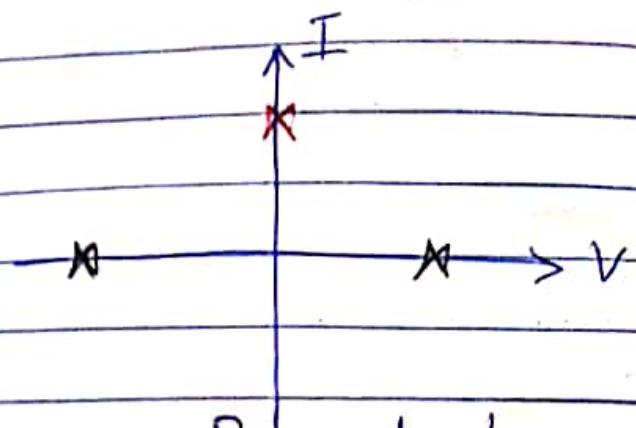
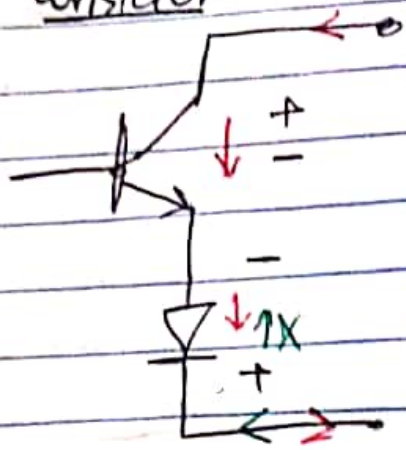
Blocking single
polarity
 \Rightarrow unipolar
switch.

Symbol for M/FET and IGBT.



Application of these three?
Voltage source inverter.

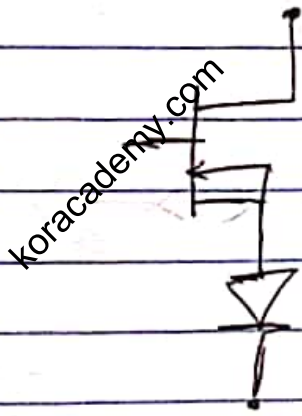
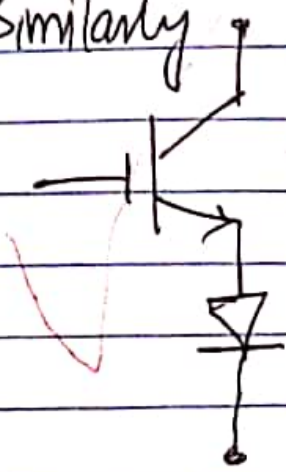
Consider



2 quadrant
unidirectional current flow
↳ Bipolar in nature.

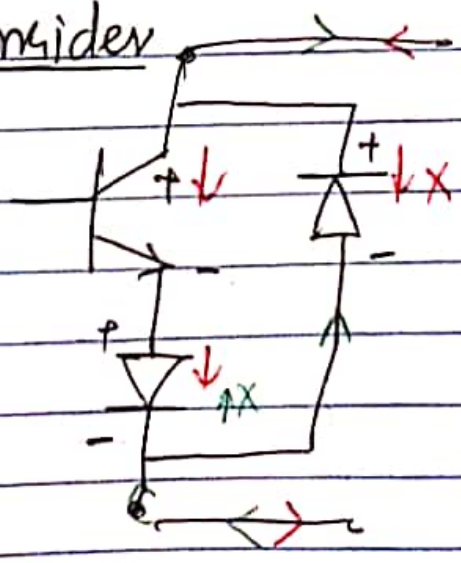
no negative voltage

Similarly

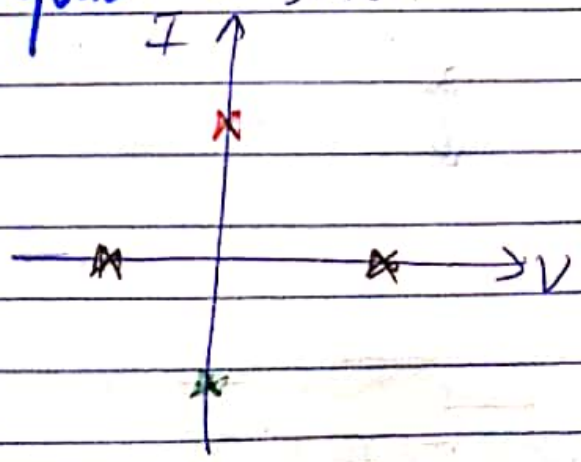


These two have the
same characteristics as
the above

Consider

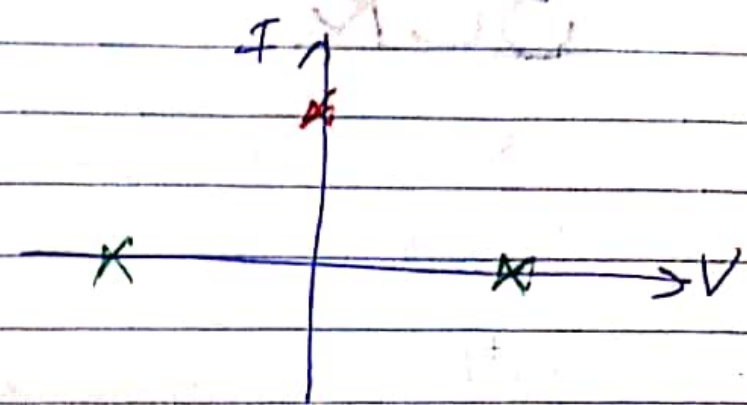
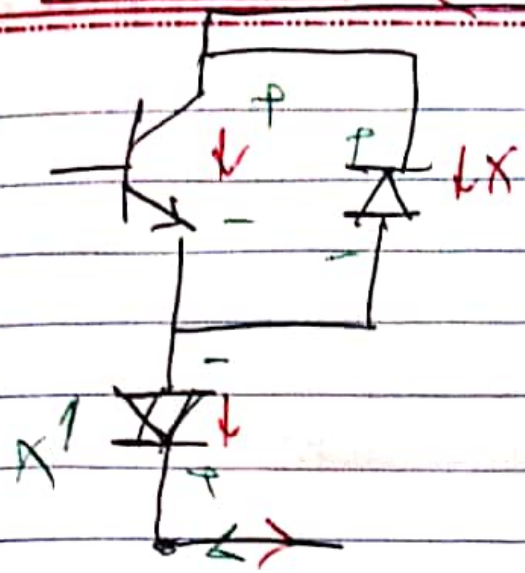


4 quadrant switch



Bidirectional current flow

Bipolar switch → block both polarities

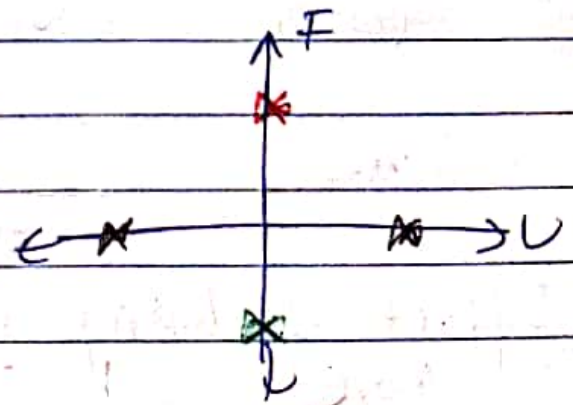
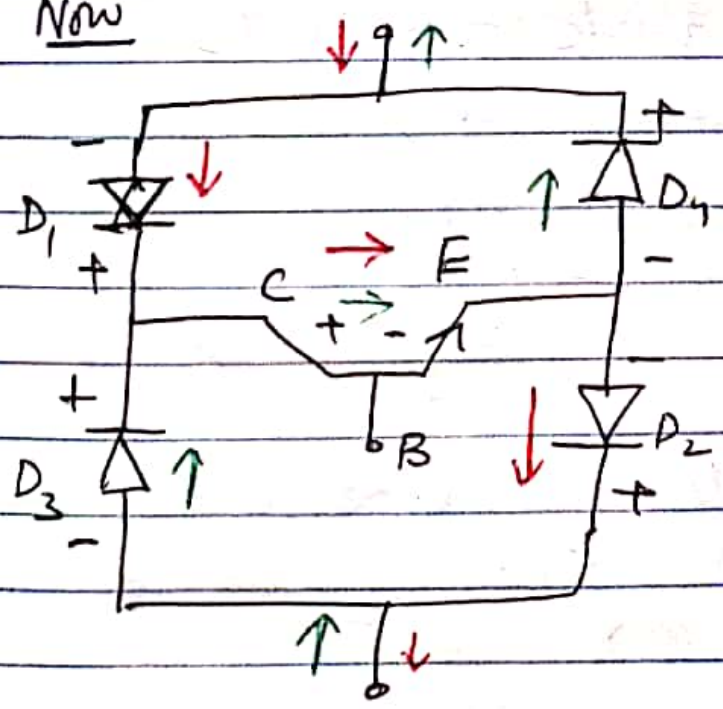


2 quadrant switch

no negative current
unidirectional current

Bipolar in nature and unidirectional current switches are used in current source inverter.

Now



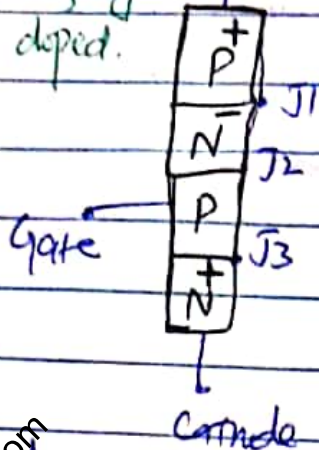
4 quadrant switch

bidirectional bipolar.

SCR

- SCR is a 4 layer device \rightarrow 3 junctions.

+ \rightarrow highly doped
- \rightarrow lightly doped.



- SCR is a 3 terminal device.

A, K \rightarrow princ. terminals

G \rightarrow control terminal

- SCR is a half controlled device.

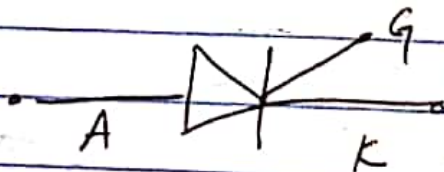
\rightarrow turn ON is controlled

- SCR is a DC switch.

does not mean that $D \leftarrow \rightarrow$ unidirectional supply \rightarrow it allows current in one direction

- Current flows from anode to cathode.
(diode is also a DC switch)

Symbol



Effect of doping ?

more doped portion contributes less in the formation of depletion layer

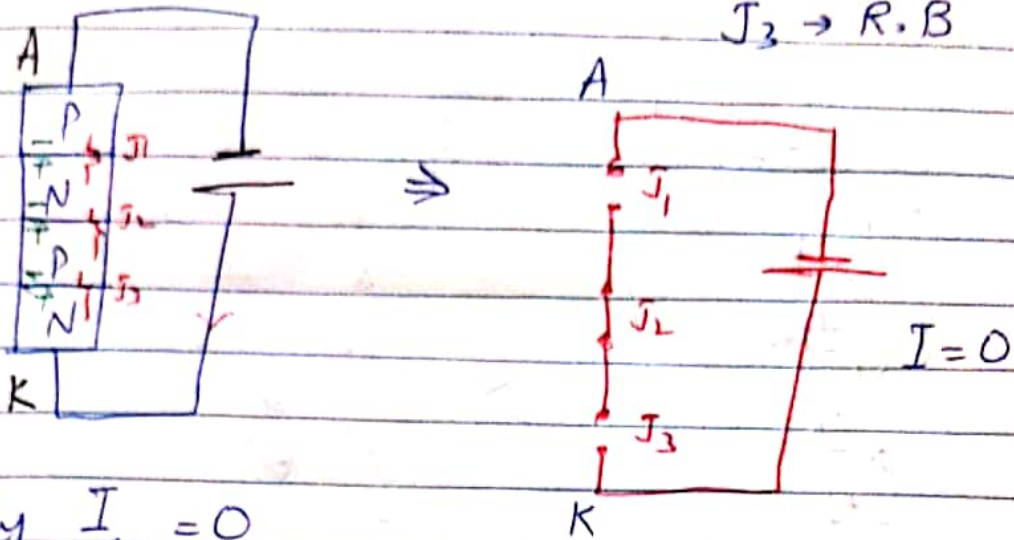
Function of SCR.

It has three modes of operation.

- (i) Reverse blocking mode. (R.B.M)
- (ii) Forward blocking mode. (F.B.M)
- (iii) Forward conduction mode. (F.C.M)

(1) RBM

$J_1 \rightarrow R.B$ $J_2 \rightarrow F.B$
 $J_3 \rightarrow R.B$



Ideally $I_{AK} = 0$

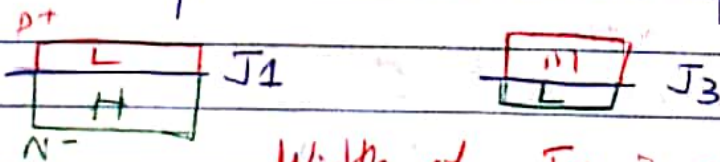
Practically $I_{AK} =$ Reverse leakage current.

What will block the voltage V ?

Both the R.B junctions will block.

But; which junction blocks more and which does less?

↳ depends on the width of depletion layer.



Width of J_1 is greater so more portion of the voltage is blocked by it.

We want current to flow.

↳ Breakdown should occur at both the junctions.

↳ increase the reverse voltage continuously.

↳ Blocking voltage of both junctions will increase.

rapid current flows ← breakdown ←

ⓑ Bebar Register

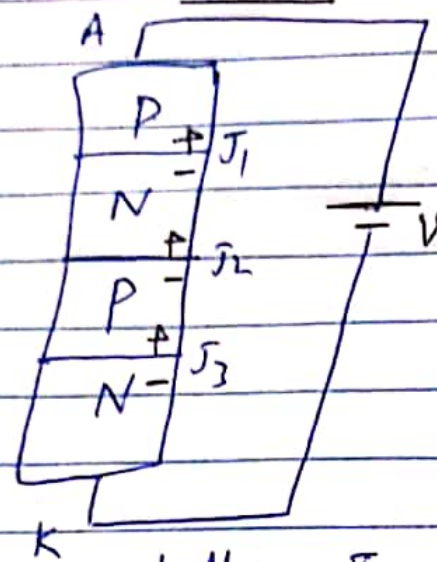


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So in R.B.M the SCR acts as an OFF switch.

(ii) F.B.M

$J_1 \rightarrow F.B$, $J_2 \rightarrow R.B$,
 $J_3 \rightarrow F.B$



Ideally $I_K = I_A$
Practically $I_A < I_K$ Forward leakage current

Total voltage is blocked by junction J_2
For current to flow,
increase the voltage V , until breakdown occurs at the junction.

↳ forward current starts flowing.

So again in F.B.M SCR acts as an OFF switch.

(iii) F.C.M

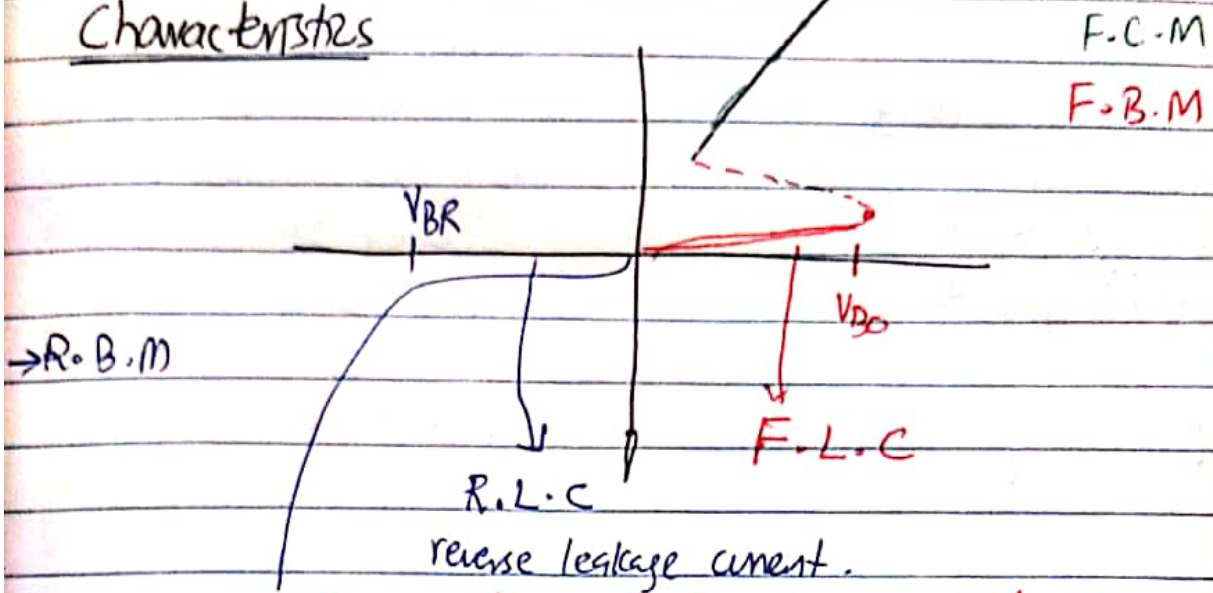
Keep on increasing $V \rightarrow$ breakdown at J_2
 \rightarrow current starts flowing from anode to cathode
 \rightarrow SCR has come into forward conduction mode

$J_1 \rightarrow F.B$ $J_2 \rightarrow R.B$ $J_3 \rightarrow F.B$

↳ achieving breakdown

No change in biasing.

Characteristics



V_{BO} → forward breakover voltage

in conduction state anode to cathode voltage is very low almost zero (KVL is not satisfied)

↳ it is never like this → there is always a limiting resistance.

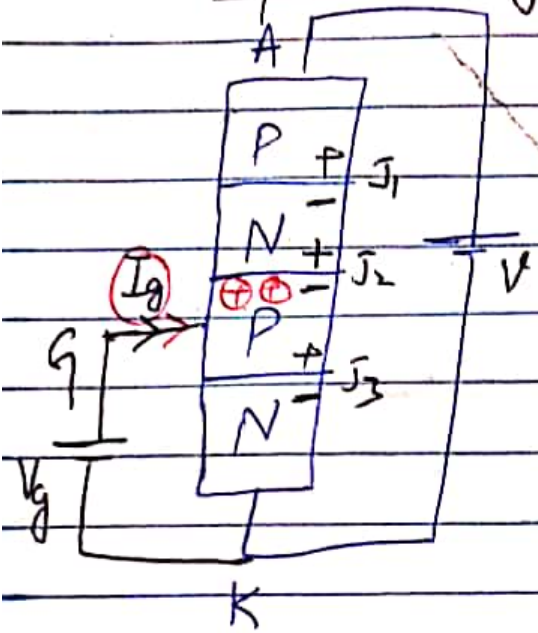
$\left\{ \begin{array}{l} V_{AK} > V_{BO} \rightarrow F.C.M \\ V_{AK} < V_{BO} \rightarrow F.B.M \end{array} \right.$

Before seeing latching and holding currents we see :

Triggering Methods of SCR
How to turn on SCR.

↳ (1) supply voltage method.
it is not advisable.

(ii) Gate triggering



Before triggering first of all forward bias the SCR i.e. it should be in the forward blocking mode.

i.e. $A = +ve$ $K = -ve$

Now connect the gate terminal to a supply!

I_g is entering +ve charge into the J_2 in the P layer.

↳ So it will neutralize the already present -ve charges.

↳ will reduce its width → so the required amount of voltage to break J_2 will decrease.

~~$V_{BO} \propto \frac{1}{\text{width of } J}$~~

$V_{BO} \propto \text{Width of junction}$

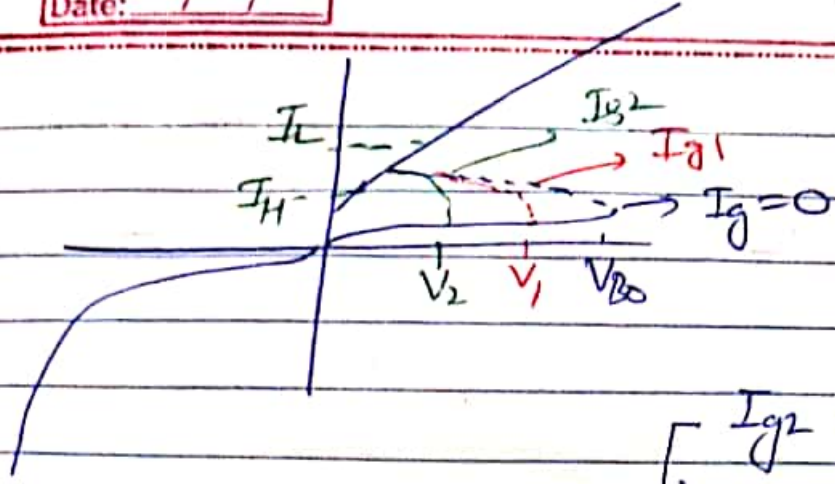
Injected charge $\propto \frac{1}{J_2 \text{ width}}$

↓

$\propto \frac{1}{V_{BO}}$

How to increase charge?

$q = it$ $i \uparrow$ or $t \uparrow$



$$\left[\begin{array}{l} I_{L2} > I_{L1} \\ \rightarrow V_2 < V_1 \end{array} \right]$$

Latching Current

The amount of current above which the SCR is in ON state. anode to cathode

if $I_{AK} \geq I_L \rightarrow \text{SCR in F.C.M} \rightarrow \text{ON}$

Holding Current

The amount of current below which if there is anode to cathode current in SCR so the SCR goes into Forward blocking state

$I_{AK} < I_H \rightarrow \text{SCR in F.B.M} \rightarrow \text{OFF}$

In b/w I_L and I_H , it is in transient state where we cannot decide whether it is turning ON or turning OFF.

I_L and I_H are provided by manufactures.

$I_L > I_H$

$\frac{I_L}{I_H} = 2 \text{ to } 3$ for SCRs above 60A rating.

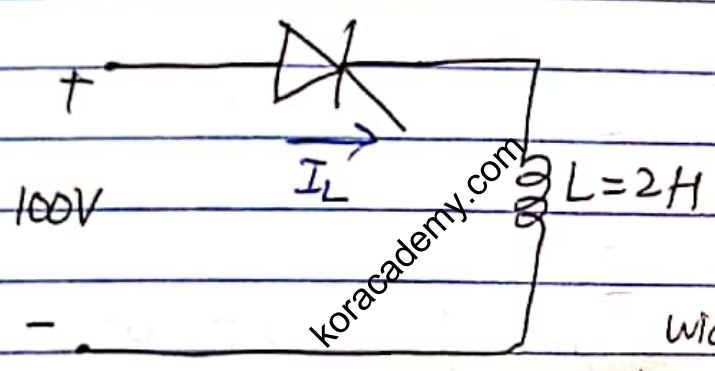
$\frac{I_L}{I_H} = 1.2 \text{ to } 1.8$ for SCRs below 60A rating.

The pulse width required (t)

$t = \frac{L \times \text{inductor current}}{V_s}$

→ this is not a formula (trick)

Q1.



latching current = 4mA

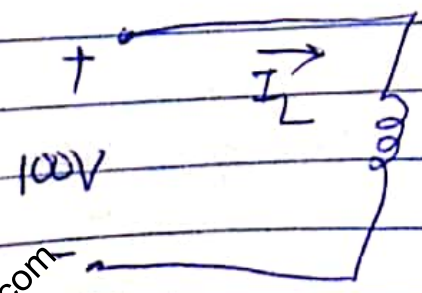
minimum pulse width required to turn ON SCR = ?

$t = \frac{2 \times 4 \times 10^{-3}}{100} = \frac{8}{10^2} \times 10^{-3} = 8 \times 10^{-5}$

$\Rightarrow t = 80 \mu s$

Conventional method.

Minimum current = $I_L \Rightarrow \text{SCR} = \text{ON} \Rightarrow$ short circuit



$V_L = L \frac{di}{dt}$

$100 = L \frac{di}{dt}$

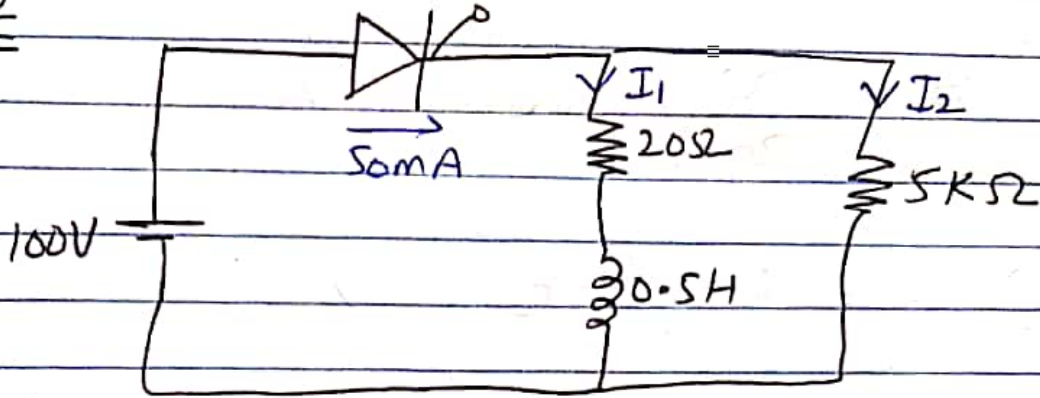
$i(t) = \int \frac{100}{L} dt$

$i(t) = 100 \times t$

$$t = \frac{L \times i(t)}{100} = \frac{2 \times 4 \times 10^{-3}}{100}$$

$$\Rightarrow t = 80 \mu s$$

Q2



Latching current = 50mA

Minimum pulse width required = ?

Method 1 $t = \frac{L \times I_{ind}}{V_s} = \frac{0.5 \times I_{ind}}{100}$ SCR

$I_L = 50mA \Rightarrow$ this is flowing through ~~inductor~~ SCR is ON \leftarrow

Once SCR is ON, the potential at all three branches is the same i.e. 100V.

$$\Rightarrow I_2 = \frac{100}{5000} = 20mA$$

$$\Rightarrow I_1 = 50 - 20 = 30mA$$

$$\Rightarrow t = \frac{0.5 \times 30 \times 10^{-3}}{100} = 1.5 \times 10^{-2} \times 10^{-3}$$

$$= 1.5 \times 10^{-4}$$

$$\Rightarrow t = 150 \mu s$$

Method 2

$$I_L = I_1 + I_2$$

$$50 \times 10^{-3} = \frac{V_s}{R_1} (1 - e^{-t/\tau}) + 20 \text{mA}$$

$$30 \text{mA} = \frac{100}{20} (1 - e^{-20t/0.5}) \quad \tau = L/R$$

$$300 \times 10^{-3} = 5 (1 - e^{-20t/0.5})$$

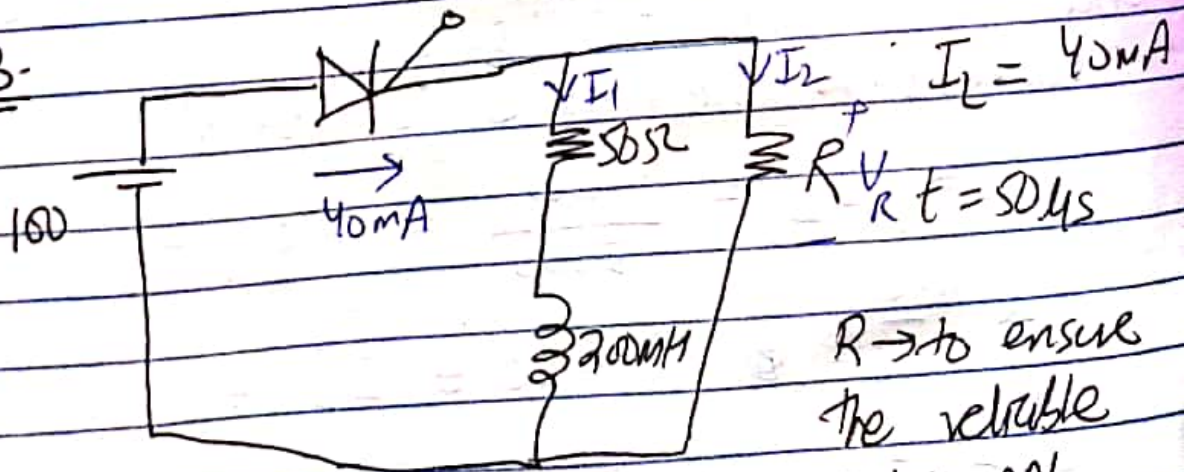
$$1 - e^{-20t/0.5} = 6 \times 10^{-3}$$

$$\ln(e^{-20t/0.5}) = \ln(1 - 6 \times 10^{-3})$$

$$\frac{-20t}{0.5} = -6.01 \times 10^{-3}$$

$$\Rightarrow t = 150 \mu\text{s}$$

Q3.



R → to ensure the reliable turn ON.

Method 1

$$50 \times 10^{-6} = \frac{200 \times 10^{-3} \times I_1}{100}$$

$$\Rightarrow I_1 = 25 \text{mA}$$

Hence $I_2 = 40 - 25 = 15 \text{ mA}$

Hence $R = \frac{V_R}{I_2} = \frac{100}{15 \times 10^{-3}}$

$\Rightarrow R = 6.67 \text{ k}\Omega$

Conventional method

$I_2 = I_L - I_1$

$I_2 = 40 \times 10^{-3} - \frac{100}{50} \left(1 - e^{-\frac{50 \times 10^{-6} \times 50}{200 \times 10^{-3}}} \right)$

$I_2 = 15.1 \text{ mA}$

$\Rightarrow I_2 = 16.5 \text{ mA}$

$R = \frac{100}{16.5 \times 10^{-3}}$

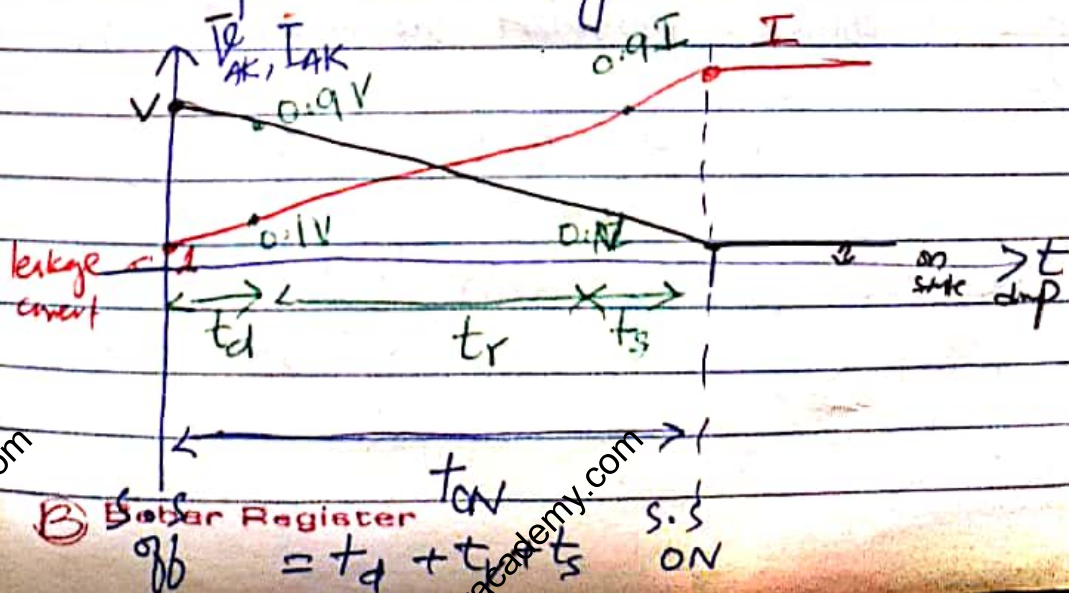
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$\Rightarrow R = 6.06 \text{ k}\Omega$

Switching characteristics of SCR

switch \Rightarrow ON to OFF or OFF to ON.

\hookrightarrow from one steady state to another.

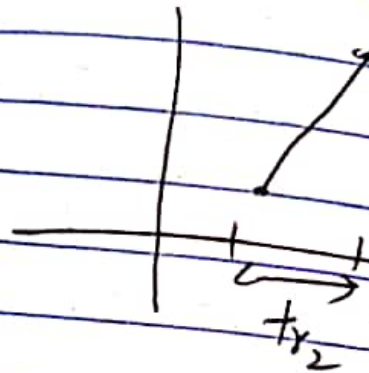


$t_d \rightarrow$ time delay $r \rightarrow r_{BE}$ $s \rightarrow$ spread

t_{on} should be minimum for fast switching.

Dominant $\rightarrow t_r \rightarrow$ most change.
For controlling t_{on} control t_r .

slope $\rightarrow \frac{di}{dt}$ $i \rightarrow I_{AK}$



slope $\uparrow \Rightarrow t \downarrow \Rightarrow t \downarrow$
 $\Rightarrow \frac{di}{dt} \uparrow \uparrow$

$t_{r2} < t_{r1}$

For reliable turn ON $\frac{di}{dt}$ must be high.
But how much high?

$\frac{di}{dt}$ is always provided by manufacturer.

let $(\frac{di}{dt})_{sp}$ specified.

let we are operating with $(\frac{di}{dt})_{op}$

$(\frac{di}{dt})_{op} < (\frac{di}{dt})_{sp} \rightarrow$ SCR is safe
 $(\frac{di}{dt})_{op} > (\frac{di}{dt})_{sp} \rightarrow$ damage

$$\text{Instantaneous power} = P(t) = V(t) i(t)$$

$$P_{avg} = \frac{1}{T} \int P(t) dt$$

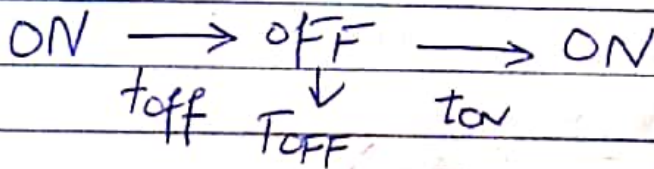
$$p(t) = V(t) i(t) = \frac{dW(t)}{dt}$$

$$dW(t) = p(t) dt$$

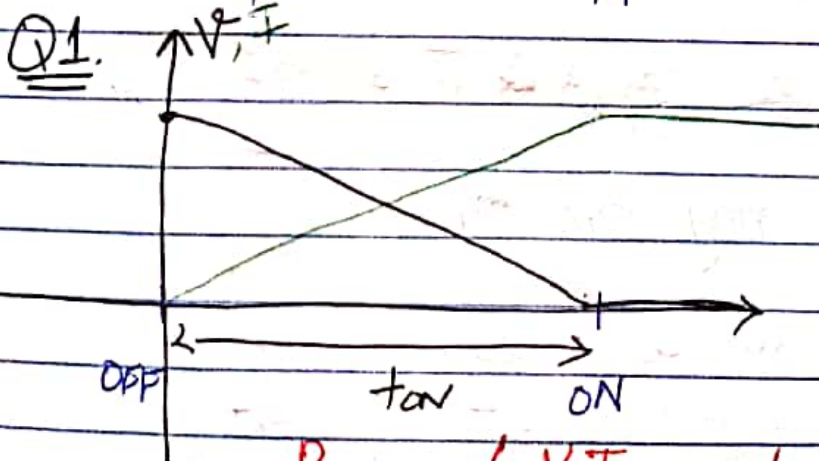
$$W(t) = \int p(t) dt$$

$$\Rightarrow P_{avg} = \frac{W(t)}{T}$$

Time period is the duration from where wave form repeats itself.
eg from going ON to ON.



$$\text{So time period} = t_{off} + T_{OFF} + t_{on}$$



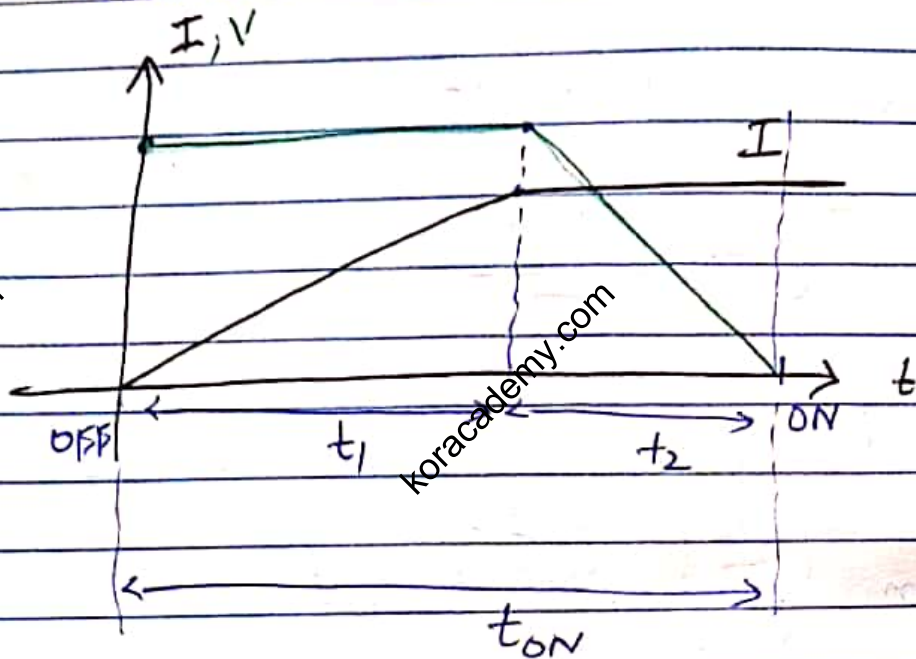
$$P_{avg} = \left(\frac{VI}{T} \cdot t_{on} \right) \text{ watt}$$

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$$\text{Energy} = P_{\text{avg}} \times T = \left(\frac{VI}{2} \cdot t_{\text{on}} \right) \text{ joules}$$

Q1 → wasq case 1 → in which voltage and current both were varying.

Q2 → case 2 → One varies the other is constant.



S.S. OFF $\Rightarrow I = 0$ S.S ON $V = 0$

$$P_{\text{avg}} = \frac{VI}{2} \left(\frac{t_{\text{on}}}{T} \right)$$

$$\text{Energy} = P_{\text{avg}} \times T = \frac{VI \cdot t_{\text{on}}}{2}$$

Q2 SCR during turn on

Anode Voltage 600V 0V

Anode Current 0A 100A

Both are varying linearly

$t_{\text{on}} = 5 \mu\text{s}$

$f = 100 \text{ kHz}$

$P_{\text{avg}} = ?$

$$T = \frac{1}{f} = \frac{1}{100} \text{ sec}$$

As linearly $P_{avg} = \left(\frac{V I}{6} \times \frac{\text{ton}}{T} \right)$

$$= \left(\frac{600 \times 100}{6} \times \frac{5 \times 10^{-6}}{100} \right)$$

$$= 106 \times 5 \times 10^{-6}$$

$$\Rightarrow P_{avg} = 5 \text{ watt.}$$

$$E = P_{avg} \times T = 5 \times \frac{1}{100} = 5 \times 10^{-2} \text{ J}$$

Conventional approach

$$P_{avg} = \frac{1}{T} \int v(t) i(t) dt$$

Expressions for $v(t)$ and $i(t)$.

$$y = -mx + c$$

$$v(t) = \frac{-600 \times t + 600}{\text{ton}}$$

$$i(t) \quad y = mx + c$$

$$i(t) = \frac{100}{\text{ton}} \times t + 0$$

$$\Rightarrow P_{avg} = \frac{1}{T} \int_0^{\text{ton}} \frac{-600 \times 100}{\text{ton}^2} \times t^2 + \frac{60000t}{\text{ton}} dt$$

$$\frac{600 \times 100}{T \times \text{ton}} \left[\frac{-1}{\text{ton}} \int_0^{\text{ton}} t^2 dt + \int_0^{\text{ton}} t dt \right]$$

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$$= \frac{600 \times 100}{T \times \tan} \left[\frac{-1}{\tan} \left(\frac{\tan^3}{3} \right) + \left(\frac{\tan^2}{2} \right) \right]$$

$$= \frac{600 \times 100}{T \times \tan} \times \tan^2 \left(\frac{1}{2} - \frac{1}{3} \right)$$

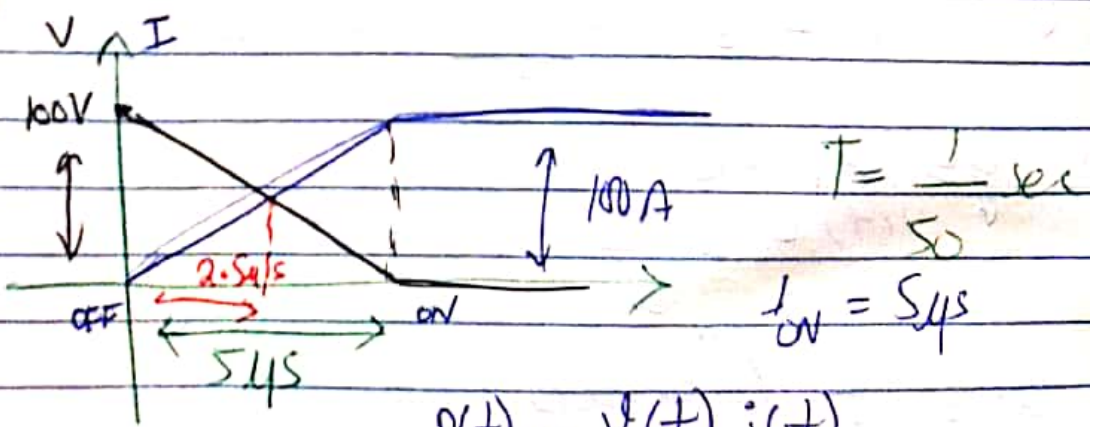
$$= \frac{600 \times 100 \times \tan}{T} \left(\frac{3-2}{6} \right)$$

$$= \frac{600 \times 100}{6} \times \tan \times \frac{1}{T}$$

$$= \frac{600 \times 100}{6} \times 5 \times 10^{-6} \times \frac{1}{100}$$

$$\Rightarrow P_{avg} = 5 \text{ watt.}$$

Q. For the switching waveform shown, state the condition at which the maximum power will occur.



$$p(t) = v(t) i(t)$$

$$y = - \left(\frac{100}{t} \right) \times t + 100 = v(t)$$

$$i(t) = \left(\frac{100}{\text{ton}} \right) t + 0$$

$$\Rightarrow P(t) = \frac{-100 \times 100}{\text{ton}} t^2 + \frac{100 \times 100 t}{\text{ton}}$$

t is the only variable \rightarrow differentiate wrt t .

$$\frac{dP(t)}{dt} = 0 = \frac{-10^4}{\text{ton}^2} \cdot 2t + \frac{10^4 \cdot 1}{\text{ton}}$$

$$\frac{2t \cdot 10^4}{\text{ton}^2} = \frac{10^4}{\text{ton}}$$

$$t = \frac{\text{ton}}{2} = 5 \text{ms}$$

$\Rightarrow t = 2.5 \text{ms} \rightarrow$ this is where maximum power will occur.

What is max power?

Put value of $t = 2.5 \text{ms}$ in power equation.

$$P(t)_{\text{max}} = P(t) \Big|_{t=2.5\text{ms}} = \frac{-10^4 \times (2.5\text{ms})^2}{(5\text{ms})^2} + \frac{10^4 (2.5\text{ms})}{(5\text{ms})}$$

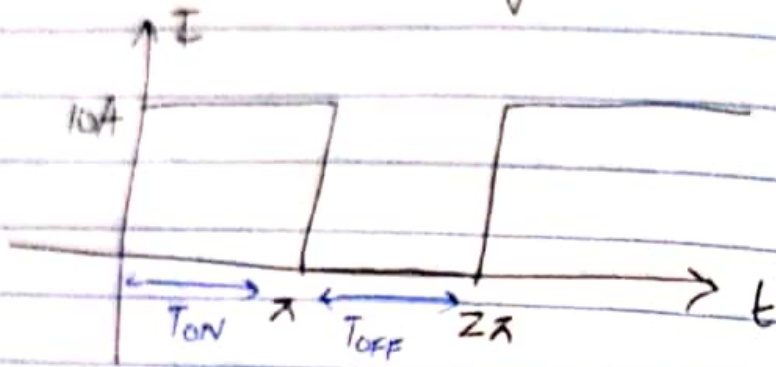
$$= -2499.98 \text{ W} \Rightarrow P(t) = 2.5 \text{ kW}$$

$$P_{\text{avg}} = \frac{100 \times 100}{6} \times 5 \times 10^{-6} \times 50$$

$$\Rightarrow P_{\text{avg}} = 0.416 \text{ W}$$

$$E = P_{\text{avg}} \times T = 8.32 \times 10^{-3} \text{ J}$$

Q. A MOSFET of rating 15A carries a periodic current as shown.
 The ON state resistance of MOSFET is 0.15 Ω . The average ON state power loss?



$$A. P_{avg} = I_{rms}^2 R = \left(\frac{10}{\sqrt{2}}\right)^2 (0.15)$$

$$\Rightarrow P_{avg} = 50 \times 0.15 = 7.50 \text{ W}$$

$I_{rms} = \text{Peak} \times \sqrt{\frac{\text{time for which exists}}{\text{total time period}}}$

As here

$$10 \times \sqrt{\frac{\pi}{2\pi}}$$

Average

Power associated term is always RMS.
 General approach.

$$P(t) = \frac{1}{T} \int V(t) i(t) dt$$

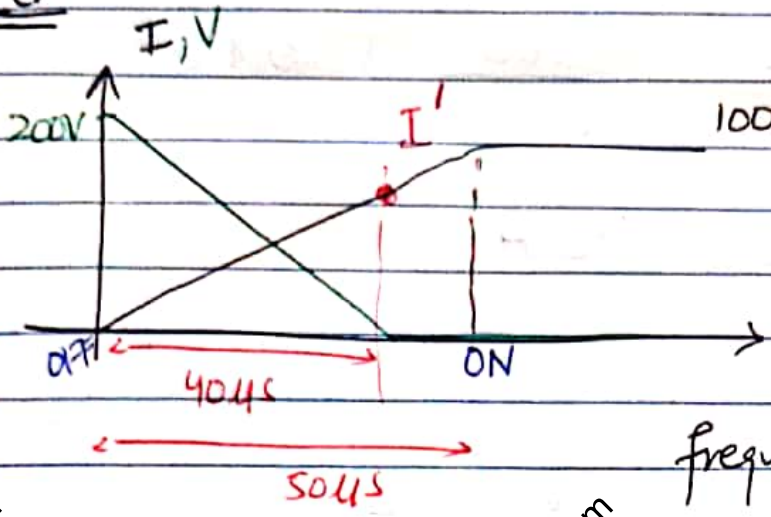
$$P(t) = \int_0^T i(t)^2 R dt = \frac{1}{2\pi} \left[\int_0^{\pi} i(t)^2 R dt \right]$$

$$= \frac{1}{2\pi} \left[\int_0^{\pi} 10^2 \times 0.15 dt + \int_{\pi}^{2\pi} 0 dt \right]$$

$$= \frac{1}{2\pi} \times 100 \times 0.15 \left(\frac{t}{0} \right)^{\pi}$$

$$= \frac{100 \times 0.15 \times \pi}{2\pi} = 7.5 \text{ W}$$

Q.



If the Avg loss is limited to 100W during its turn on time. then switching frequency will be ?

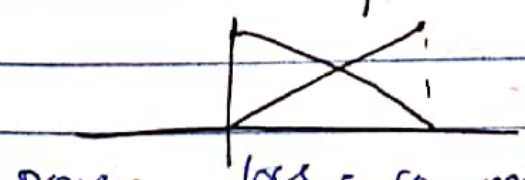
$P_{avg} = 100 \text{ W}$ during ton

$$P_{avg} = \frac{VI}{6} \times \frac{t_{on}}{T}$$

$$100 = \frac{200 \times 100}{6} \times \frac{50}{T}$$

$$T = \frac{100 \times 6}{200 \times 100 \times 50} \Rightarrow T = 6 \times 10^{-4} \text{ Hz}$$

because this formula is for $V \uparrow I \downarrow$
 $I \uparrow V \downarrow$



After I' there is no power loss; so modifying the above formula

$$100 = P_{avg} = \frac{200 \times I'}{6} \times \frac{40 \times 10^{-6}}{T}$$

We need to calculate I' first.

Equation $y = mx + c$

$$i(t) = \left(\frac{100}{50 \times 10^{-6}} \times t \right) + 0$$

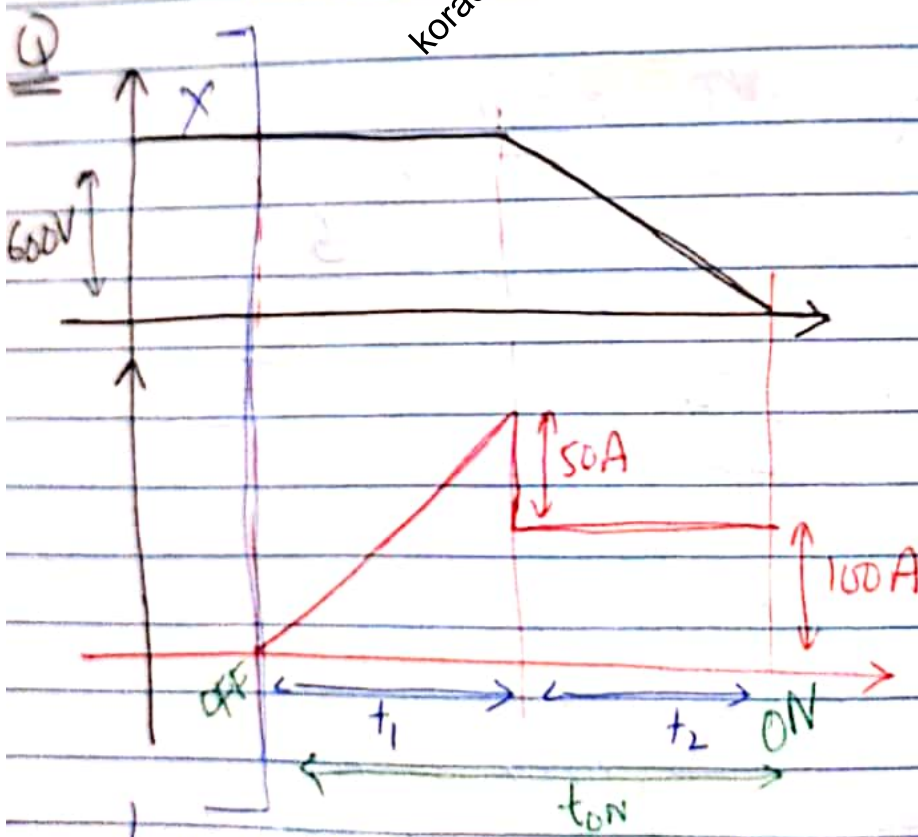
At $t = 40 \mu s$ to find I'

$$i(40 \mu s) = I' = \frac{100}{50 \times 10^{-6}} \times 40 \times 10^{-6}$$

$$\Rightarrow I' = 80 A$$

$$\Rightarrow P_{avg} = 100 = \frac{200 \times 80 \times 40 \times 10^{-6} \times 1}{T}$$

$$\Rightarrow \frac{1}{T} = f = 937.5 \text{ Hz.}$$



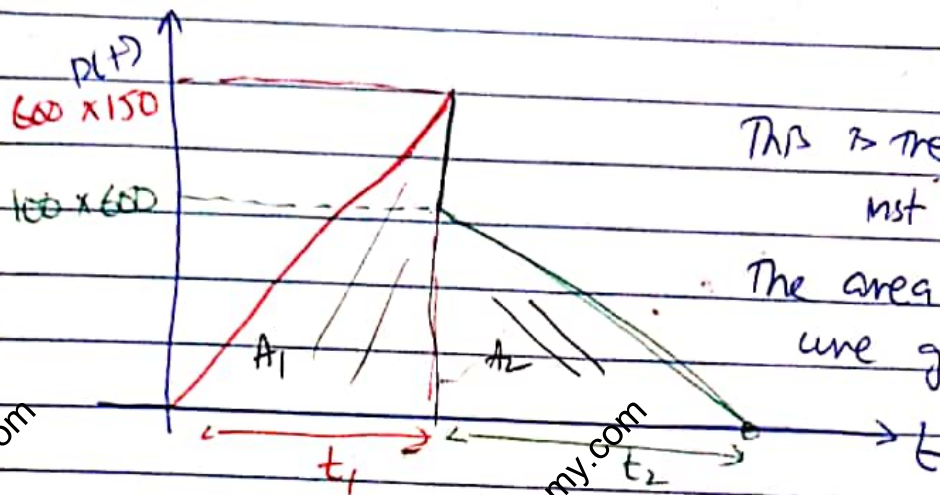
$\hookrightarrow x \rightarrow I = 0 \rightarrow$ no power loss

$$P = \frac{VI}{2} \left(\frac{t_1 + t_2}{T} \right) = \frac{VI}{2} \times \frac{t_{ON}}{T}$$

$$E = P_{avg} \times T = \frac{VI}{T} \times (t_1 + t_2)$$

$$E = \int P(t) dt = \int v(t) i(t) dt$$

$P(t) = v(t) i(t)$



$$E = A_1 + A_2$$

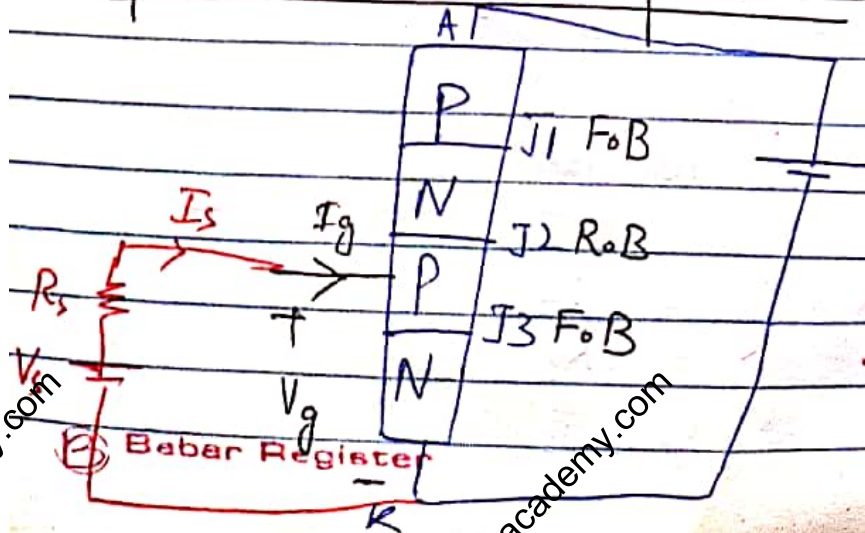
$$E = \frac{1}{2} \times 600 \times 150 \times t_1 + \frac{1}{2} \times 100 \times 600 \times t_2$$

$$t_1 = 14\mu s \quad t_2 = 14\mu s$$

$$\Rightarrow E = 0.0453 = 45 \text{ mJ}$$

Sir $\rightarrow 75 \text{ mJ}$

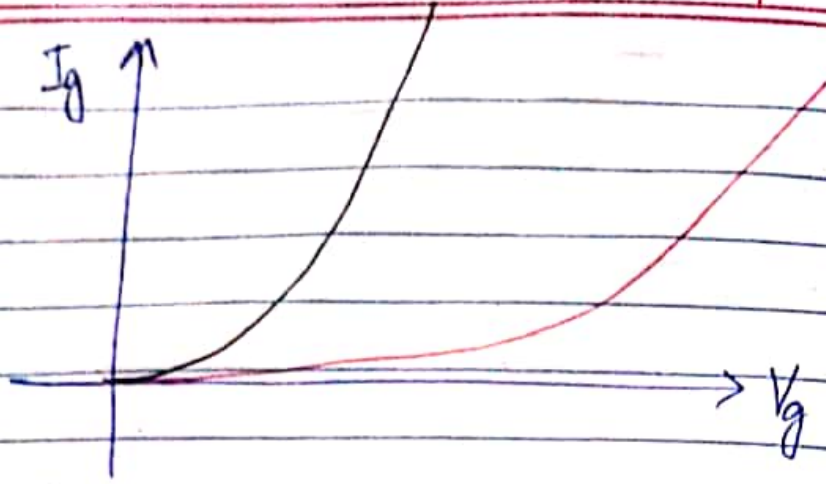
Gate characteristics of SCR



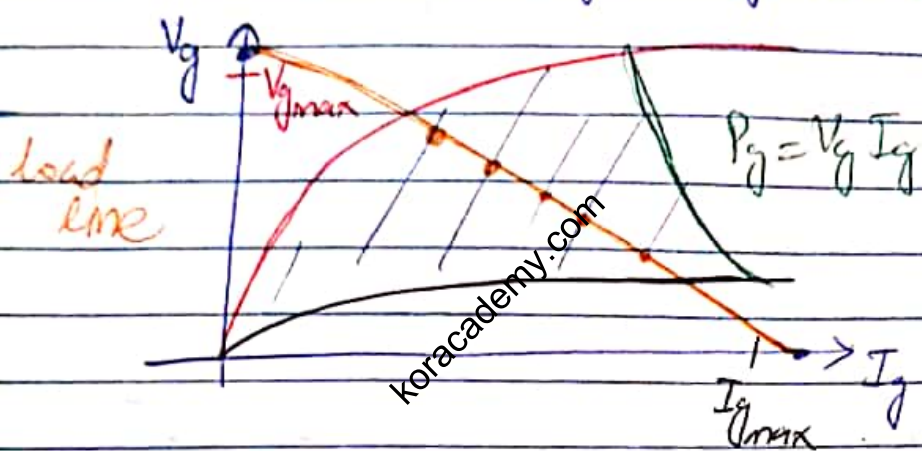
3/w gate and cathode we have PN junction in forward bias

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heavily doped junction
lightly doped region



The same curve on V_g vs I_g (in amps).



$$P_g(\text{avg}) = V_g I_g = \text{constant}$$

↳ so the chs lie within.

To provide I_g we need to connect a source.

$$\Rightarrow I_g = I_s$$

$$V_s = I_s R_s + V_g$$

$$V_s = I_g R_s + V_g$$

↳ finding load line from here.

$$V_g = 0 \Rightarrow I_g = \frac{V_s}{R_s}$$

$$I_g = 0 \Rightarrow V_g = V_s \quad (V_s > V_g)$$

In slope form $V_g = V_s - I_g R_s$

$m = R_s$
 ↳ negative slope

$y = c - mx$

V_g V_s I_g ch (// //) wherever touches the load line gives the ϕ point.

- V_s → gate source voltage
- I_s → gate source current
- R_s → gate source resistance
- V_g → gate voltage
- I_g → gate current or triggering current

Two types of SCR triggering.

- Continuous pulse triggering.
- Pulse gate triggering.

Gate signal is required till anode to cathode current becomes greater than the latching current.

- ↳ once it does, you don't need the gate pulse anymore
- ↳ SCR is ON.

If SCR becomes ON and still you don't remove the gate pulse → this is continuous pulse triggering



Preferable for highly inductive loads.

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$$t = L \times \text{Inductance}$$

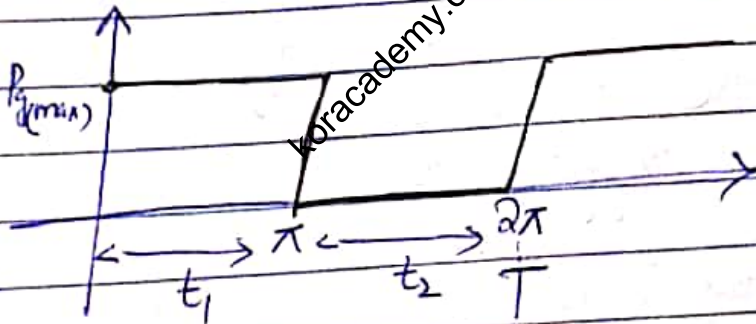
V_g

$$L \uparrow \Rightarrow t \uparrow \uparrow$$

In such type of signals (ie unstart)

$$P_{g(\text{avg})} = V_g I_g = P_{g(\text{max})}$$

- When the SCR goes ON (ie $I_{AK} > I_2$) and you remove the gate pulse, this is called pulse gate triggering.



$$P_{g(\text{max})} = (V_g \cdot I_g) \rightarrow \text{instantaneous}$$

$$\text{Here } P_{g(\text{avg})} = V_g \cdot I_g \quad \times$$

$t_1 \rightarrow$ time for which gate signal is applied.

$t_2 \rightarrow$ " " " " removed.

$$P_{g(\text{avg})} = P_{g(\text{max})} \times \frac{t_1}{T} = V_g I_g \cdot \frac{t_1}{T}$$

$$\text{Duty cycle} = \frac{\text{on time}}{\text{total period}} = \frac{t_1}{T}$$

Here

$$\Rightarrow P_g(\text{avg}) = D \cdot P_g(\text{max})$$

Practically

SCR triggering is approximately 10 KHz.

$$\text{Hence } T = \frac{1}{f} = 100 \mu\text{s}$$

Hence if $t_1 < 100 \mu\text{s} \rightarrow$ pulse gate triggering.

$$\text{Here } P_g(\text{avg}) < P_g(\text{max})$$

$$P_g(\text{avg}) = D \cdot P_g(\text{max})$$

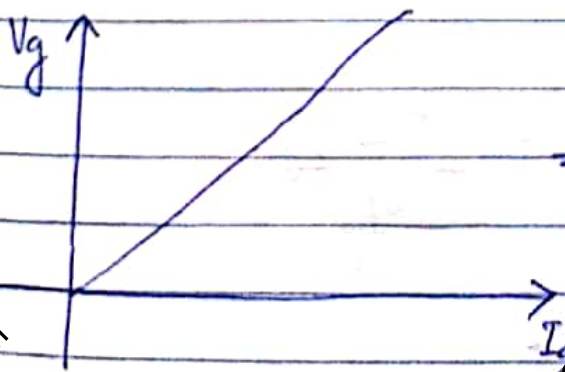
$$\text{where } P_g(\text{max}) = V_g I_g$$

$t_1 > 100 \mu\text{s} \rightarrow$ continuous pulse triggering

$$\text{Here } P_g(\text{avg}) = P_g(\text{max}) = V_g I_g$$

$$\text{As } D = 1$$

Q. I_g vs V_g char of an SCR is a straight line passing through origin with a gradient of 2.5×10^3 . If $P_g = 0.015 \text{ W}$, the value of gate voltage is?



gradient = slope

$$\rightarrow \frac{V_g}{I_g} = 2.5 \times 10^3 \quad \text{--- (1)}$$

$$P_g = V_g \cdot I_g = 0.015 \quad \text{--- (2)}$$

① in ② $\Rightarrow 2.5 \times 10^3 \times I_g^2 = 0.015$
 putting $V \Rightarrow I_g = 2.4 \text{ mA}$

→ similarly if put value of I

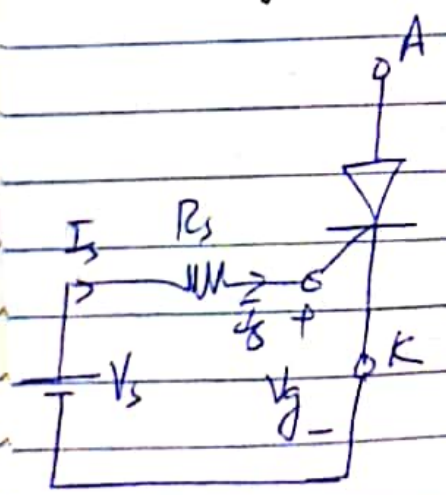
$$\frac{V_g \times V_g}{2.5 \times 10^3} = 0.015$$

$$\Rightarrow V_g = 6.125 \text{ V}$$

Q. For SCR gate cathode X_{T2S} is
 $V_g = 10 I_g + 1 \rightarrow ①$

The gate source voltage a pulse of 15 V with 20 μs of an average power dissipation is 0.3 W and peak power is 5 W.

The value of R_s to be connected in series with SCR gate terminal is ?



$t_f = 20 \mu\text{s}$
 $P_g(\text{avg}) = 0.3 \text{ W}$
 $P_g(\text{max}) = 5 \text{ W}$

$P_g(\text{avg}) < P_g(\text{max})$

\Rightarrow this is pulse gate triggering (e.g.T)

$$R_s = \frac{V_s - V_g}{I_s / I_g} = \frac{15 - V_g}{I_g}$$

We know that in P.T.

$P_g(\text{max}) = V_g \cdot I_g = 5 \rightarrow ②$

$$\textcircled{2} \text{ m } \textcircled{1} \Rightarrow V_g = 10 \times \frac{5}{V_g} + 1$$

$$V_g^2 = 50 + V_g$$

$$\Rightarrow V_g^2 - V_g - 50 = 0$$

$$V_g = 7.588 \text{ V} \rightarrow \text{second root?}$$

$$\hookrightarrow \Rightarrow I_g = 0.6588 \text{ A}$$

$$\Rightarrow R_s = \left(\frac{15 - 7.588}{0.6588} \right) = 11.25 \Omega$$

for duty cycle

$$\text{A } P_{g(\text{avg})} = D P_{g(\text{max})}$$

$$\Rightarrow D = \frac{P_{g(\text{avg})}}{P_{g(\text{max})}} = \frac{0.3}{5} = 0.06$$

Triggering frequency

$$\text{A } D = \frac{t_1^{\uparrow}}{T}$$

$$\Rightarrow \frac{1}{T} = \frac{D}{t_1^{\uparrow}} = \frac{0.3}{20 \times 10^{-6}}$$

$$\Rightarrow f = 15 \text{ kHz}$$

Time period

$$T = \frac{1}{f} = \frac{1}{3 \times 10^3} = 0.3 \mu\text{sec}$$

Rectifiers

(P) fixed AC = amplitude does not change.
Rectifier converts fixed AC to DC.

fixed AC → DC

fixed DC

Variable DC

average = fixed

average ≠ fixed

Uncontrolled rectifier

Controlled Rect.

↳ diodes are used

two type

1 φ

3 φ

SCR

SCR + diode

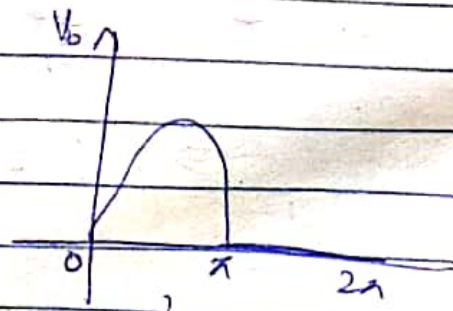
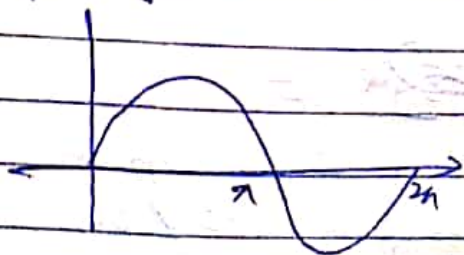
1 φ 3 φ

Semiconverter

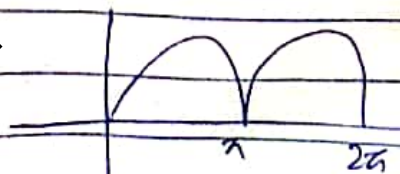
1 φ 3 φ

(ii) Output pulse

1st ip cycle



1 pulse converter.



↳ 2 pulse converter

How much of the output pulse is being created in one cycle of input.

$$T_o = \frac{2\pi}{n} \quad n \rightarrow \text{no. of pulses}$$

$$f_o = n f_s$$

(iii) Firing angle (α)

It is the point at which the device will start conduction.

$$\text{At } \omega t = \alpha \Rightarrow i_{\text{device}} = 0A$$

Extinction angle (β)

The point at which device will stop its conduction.

$$\text{At } \omega t = \beta \Rightarrow i_{\text{device}} = 0A$$

Conduction Angle (γ)

$$\gamma = \beta - \alpha$$

The time for which device has conducted.

(iv) Circuit turn off time ($t_{\text{turn off}}$)

The duration during which the device is under reverse bias condition.

→ related with SCR.
 ↳ -ve voltage
 ↳ due to available supply voltages

$$(i) V_s = V_m \sin \omega t$$

$$(ii) E = \text{battery voltage.}$$

(V) To turn ON any device especially
 Diode and SCR
 ↓ ↓
 F.B voltage F.B voltage + Firing pulse

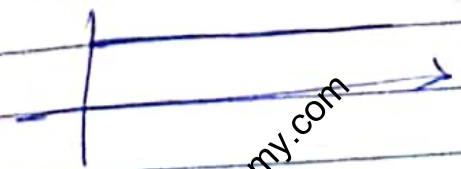
Turn OFF is decided by current.
 Reverse bias negative voltage does not decide the turning OFF of the device.

→ Once the device gets ON; then.

(vi) [Source impedance is negligible.
 All ~~the~~ devices are ideal.
 $I_H = 0A$
 → assumptions

(vii) Continuous conduction
 ↳ is decided by the output current.
 If o/p current $\neq 0$ anywhere
 ↳ this is continuous conduction

Continuous conduction ripple free
 o/p $I \neq 0$ and it is at a fixed amount
 ie pure DC \rightarrow no AC component.



continuous ~~discontinuous~~ conduction is always for current.

Discontinuous conduction.

i_p current = 0 somewhere in the graph.

↳ discontinuous mode of operation.

R and RE load → discontinuous conduction.
except in 3 ϕ rectifier.

RL, RLE or L load → can give any type of conduction.

b/c inductor → storing capability. (energy)

L → continuous.

(viii) Whenever there is inductor in the load (eg RL, RLE, L),

- The device will always conduct even when the reverse voltage is there.

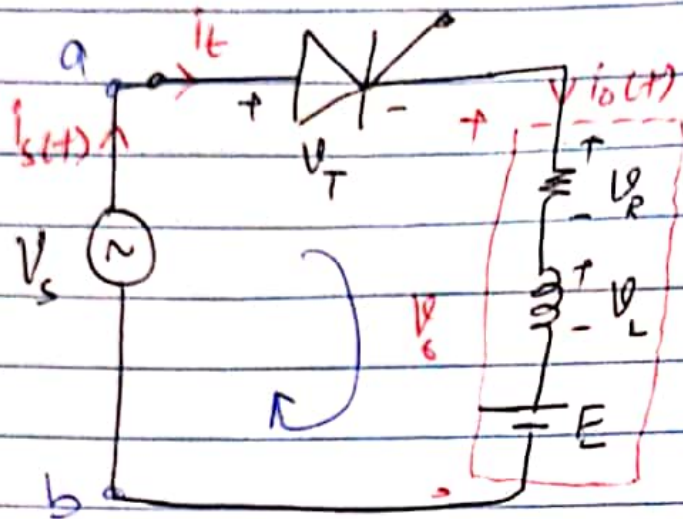
+ve voltage across device → inductor absorbs energy
-ve voltage " " → inductor supplies energy.

L in load ⇒ conduction will be there even after some time the -ve voltage has started.

↳ R.B

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1 ϕ Half Wave Controlled Rectifier with RLE load.



$$V_s = V_m \sin \omega t$$

KVL in the loop

$$V_s(t) = V_T + V_o(t)$$

$$0 \leftarrow V_o(t) = i_o(t)R + L \frac{di_o(t)}{dt} + E$$

$$V_{ab} = V_s(t) = V_m \sin \omega t$$

$$V_{ba} = -V_m \sin \omega t$$

For SCR to be ON $A = +ve$ $K = -ve$

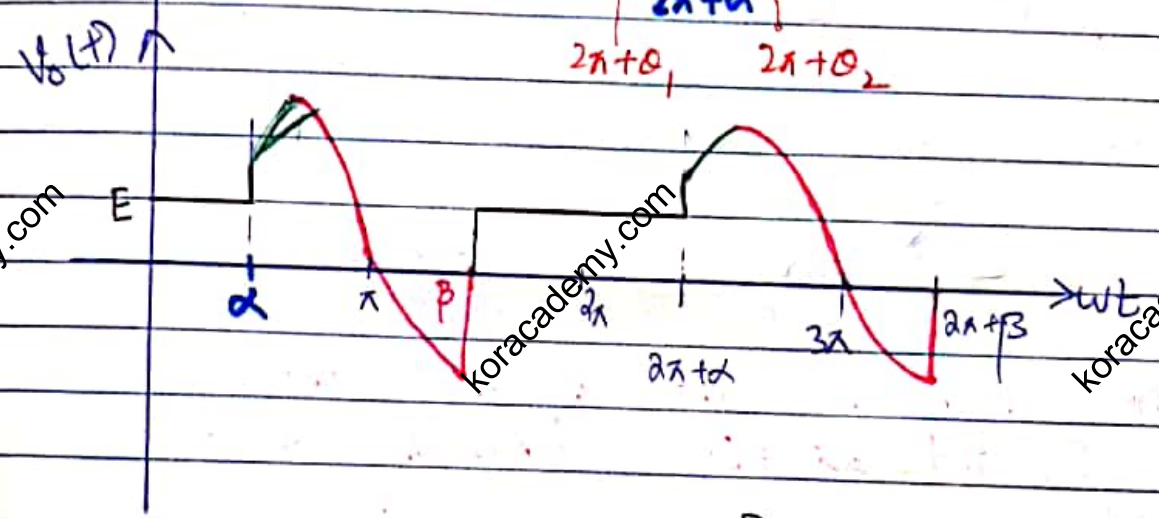
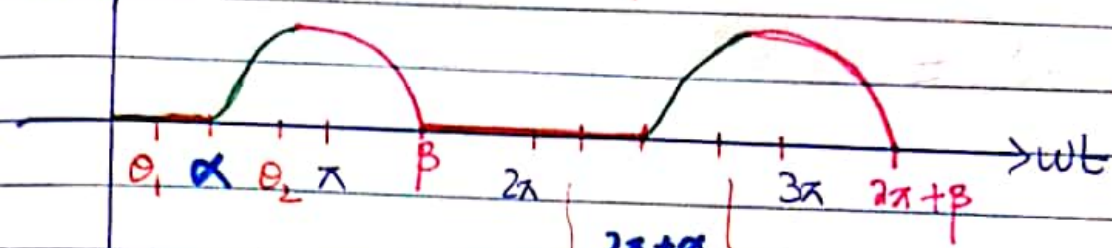
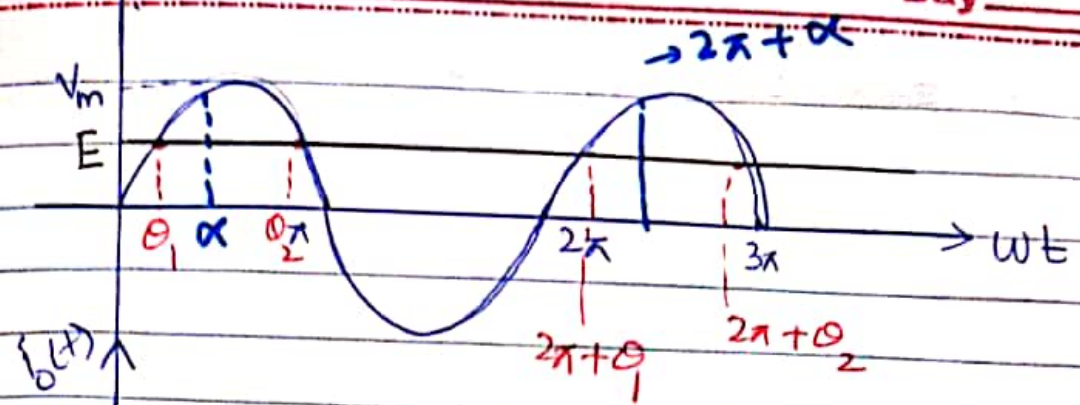
$\Rightarrow V_T = +ve \rightarrow SCR = F.O.B$

$ON \leftarrow \alpha \leftarrow \rightarrow F.O.B.M$

$$\text{At } \theta_1, V_m \sin \theta_1 = E$$

$$\theta_1 = \sin^{-1} \left(\frac{E}{V_m} \right)$$

$$\theta_2 = 180^\circ - \theta_1$$



$0 \leq \omega t \leq \theta_1 \rightarrow V_s < E \rightarrow B.M \rightarrow \text{off}$
 $i_o(t) = 0A$
 $\Rightarrow V_o(t) = E$ from ①

$\theta_1 \leq \omega t \leq \theta_2, V_s > E \rightarrow$ forward bias
 so the SCR could turn ON if gate pulse \leftarrow mode
 b applied.

But before α
 i.e. $\omega_1 \leq \omega t < \alpha \rightarrow V_s > E \rightarrow F.B.M$
 $i_o(t) = 0A$ OFF \leftarrow
 $V_o(t) = E$

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$\alpha \leq \omega t \leq \theta_2$ $V_s > E \Rightarrow$ F.C.M
ON state \downarrow

$i_o(t) \neq 0 \rightarrow$ will increase $\rightarrow V_T = 0$

$$V_o(t) = V_m \sin \omega t$$

$\theta_2 \leq \omega t \leq 2\pi + \theta_1$ $V_s < E \rightarrow$ ~~R.B.M~~

\hookrightarrow reverse bias. although both are +ve

reverse voltage $I_{SCR} \neq 0$ at θ_2

\hookrightarrow because L.

Current direction never changes along L.

$L \uparrow E \downarrow$ $L \downarrow E \uparrow$

The extinction point can arise anywhere b/w θ_1 and $2\pi + \theta_1$ depending on the value of L.

Output voltage

Whenever the SCR is ON (α to β) output voltage is equal to the supply voltage.

The current wave is not a sine wave \rightarrow it is a function of sine and exponential.

Here firing angle α

Extinction angle β

$$\text{conduction angle } \gamma = \beta - \alpha$$

$$\text{conduction time } t_c = \frac{\beta - \alpha}{\omega}$$

$$t_{\text{cut off}} = \frac{2\pi + \theta_1 - \beta}{\omega}$$

PIV = peak inverse voltage
 ↳ peak value of the reverse voltage applied.

$$R.B \rightarrow \beta \text{ to } 2\pi + \theta_1$$

$$PIV = -(V_m + E)$$

How?

$$\text{KVL} \quad V_m \sin \omega t = V_f + V_o$$

$$V_f = V_m \sin \omega t - V_o$$

$$= V_m \sin \omega t - E$$

• $\sin \omega t = 1$ for max

$$V_f = -V_m - E$$

$$I_{\text{avg}} = \frac{1}{T} \int_{\beta}^{\alpha} \frac{V_m \sin \omega t - E}{R} d\omega t$$

$$I_{\text{avg}} = \frac{1}{2\pi} \int_{\alpha}^{\beta} \frac{V_m \sin \omega t - E}{R} d\omega t$$

↳ no need to take L in average.

$$I_{\text{avg}} = \frac{1}{2\pi R} [V_m (\cos \alpha - \cos \beta) + E (\alpha - \beta)]$$

The average inductor voltage is always zero.

$$V_o = i_o(R) + L \frac{di}{dt} + E$$

$$V_{o(\text{avg})} = I_{o(\text{avg})} \cdot R + E$$

Data: / /

→ controlled RLE

How to get all relations of 1 ϕ Half Wave rectifiers.

Firing angle = α

Extinction angle = β

Conduction $\gamma = \beta - \alpha$

$$t_c = \frac{\beta - \alpha}{\omega}$$

$$t_{avg} = \frac{2\pi + \theta_1 - \beta}{\omega}$$

$$|AV| = V_m + E$$

$$I_{avg} = \frac{1}{2\pi R} [V_m (\cos \alpha - \cos \beta) + E (\alpha - \beta)]$$

$$V_{avg} = I_o R + E$$

For uncontrolled rectifiers

$$\alpha = \theta_1 = \sin^{-1} \left(\frac{E}{V_m} \right)$$

↳ any load.

For controlled and uncontrolled;

$$\beta = \theta_2 \text{ for R and RE load.}$$
$$= 180^\circ - \theta_1$$

$$\beta > \theta_2 \text{ for RL or RLE load.}$$

(i) Controlled with RL load

Firing angle = α

Extinction angle = $\beta > \theta_2$

As $\theta_1 = \sin^{-1} \left(\frac{E}{V_m} \right)$

$$E = 0 \Rightarrow \theta_1 = 0^\circ$$

$$\theta_2 = 180^\circ - \theta_1 \Rightarrow \theta_2 = 180^\circ$$

$$\Rightarrow \beta > 180^\circ$$

Conduction $\gamma = \beta - \alpha$ $t_c = \frac{\beta - \alpha}{\omega}$

$$t_{\text{cut-off}} = \frac{2\pi + 0 - \beta}{\omega} = \frac{2\pi - \beta}{\omega}$$

$$\text{PIV} = V_m$$

$$I_{\text{avg}} = \frac{1}{2\pi R} [V_m (\cos \alpha - \cos \beta)]$$

$$V_{\text{avg}} = I_{\text{avg}} R$$

(ii) Uncontrolled RL Load.

$$\theta_1 = \sin^{-1}\left(\frac{0}{V_m}\right) = 0 \quad \theta_2 = 180^\circ$$

$$\text{Firing angle, } \alpha = \theta_1 = 0^\circ$$

$$\text{Extinction angle, } \beta = \beta > \theta_2$$

$$\Rightarrow \beta > 180^\circ$$

$$\text{Conduction angle, } \gamma = \frac{\beta - \alpha}{\gamma} = \frac{\beta}{\gamma}$$

Circuit turn OFF time is not defined for uncontrolled ie diode.

$$\text{PIV} = V_m$$

$$I_{\text{avg}} = \frac{1}{2\pi R} [V_m (1 - \cos \beta)]$$

$$V_{\text{avg}} = I_{\text{avg}} R$$

(iii) Un Controlled With R Load

$$\theta_1 = \sin^{-1}\left(\frac{0}{V_m}\right) = 0 \quad \theta_2 = 180^\circ$$

Firing angle $\alpha = \theta_1 = 0^\circ$

Extinction $\beta = \theta_2 = 180^\circ$

$$t_c = \frac{\beta - \alpha}{\omega} = \frac{\pi}{\omega}$$

$$PIV = V_m + 0 = V_m$$

$$I_{o\text{avg}} = \frac{1}{2\pi R} [V_m(1+1) + 0] = \frac{2V_m}{2\pi R}$$

$$I_{o\text{avg}} = \frac{V_m}{\pi R}$$

$$V_o = I_o R = \frac{V_m}{\pi R} \cdot R \Rightarrow \boxed{V_o = \frac{V_m}{\pi}}$$

(iv) Controlled rectifier with R Load

$$\theta_1 = 0^\circ \quad \theta_2 = 180^\circ$$

Firing angle = α Extinction $\beta = \theta_2 = 180^\circ$

$$t_c = \frac{180^\circ - \alpha}{\omega} + \frac{2\pi + 0 - 180^\circ}{\omega}$$

$$\Rightarrow \frac{t}{\text{cut-off}} = \frac{\pi}{\omega}$$

$$I_{o\text{avg}} = \frac{1}{2\pi R} [V_m(\cos \alpha - (-1))] + I_{o\text{avg}} R$$

$$V_o = I_{o\text{avg}} R$$

(v) Controlled with RE load

$$\theta_1 = \sin^{-1} \left(\frac{E}{V_m} \right), \quad \theta_2 = 180^\circ - \theta_1$$

Firing angle = α Extinction angle = $\beta = \theta_2 = 180^\circ - \theta_1$

$$t_c = \frac{\beta - \alpha}{\omega} = \frac{\theta_2 - \alpha}{\omega} = \frac{180^\circ - \theta_1 - \alpha}{\omega}$$

$$t_{\text{off}} = \frac{2\pi + \theta_1 - \beta}{\omega} \quad \text{PIV} = V_m + E$$

$$I_{o \text{ avg}} = \frac{1}{2\pi R} \left[V_m (\cos \alpha - \cos \theta_2) + E (\alpha - \theta_2) \right]$$

$$V_{o \text{ avg}} = I_{o \text{ avg}} R + E$$

(vi) Uncontrolled with RE load

$$\theta_1 = \sin^{-1} \left(\frac{E}{V_m} \right) \quad \theta_2 = 180^\circ - \theta_1$$

Firing angle (α) = θ_1

↳ (start)

Extinction angle $\beta = \theta_2 = 180^\circ - \theta_1$

$$t_c = \frac{\beta - \alpha}{\omega} = \frac{180^\circ - \theta_1 - \theta_1}{\omega}$$

$$\text{PIV} = V_m + E$$

$$I_{o \text{ avg}} = \frac{1}{2\pi R} \left[V_m (\cos \theta_1 - \cos \theta_2) + E (\theta_1 - \theta_2) \right]$$

$$V_{o \text{ avg}} = I_{o \text{ avg}} R + E$$

Date: / /

(vii) Uncontrolled RLE load

$$\theta_1 = \sin^{-1}\left(\frac{E}{V_m}\right), \quad \theta_2 = 180^\circ - \theta_1$$

Firing angle $\alpha = \theta_1$

Extinction angle $\beta > \theta_2$

$$t_c = \frac{\beta - \alpha}{\omega} = \frac{\beta - \theta_1}{\omega}$$

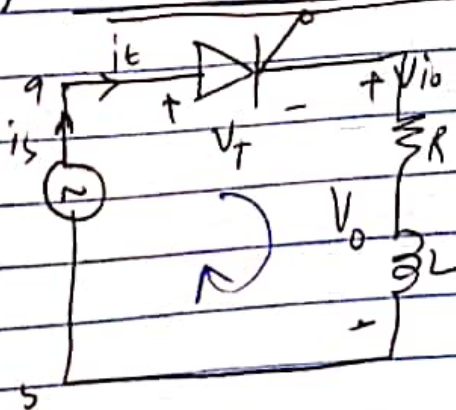
$$PIV = V_m + E$$

$$I_{o\text{ avg}} = \frac{1}{2\pi R} \left[V_m (\cos\theta_1 - \cos\beta) + E (\theta_1 - \beta) \right]$$
$$V_{o\text{ avg}} = I_{o\text{ avg}} R + E$$

3/11/19

How to Draw Waveforms for any load

(i) Controlled with RL load



$$V_{ab} = V_s = V_m \sin \omega t$$

$$V_{ba} = -V_m \sin \omega t$$

SCR can be one of

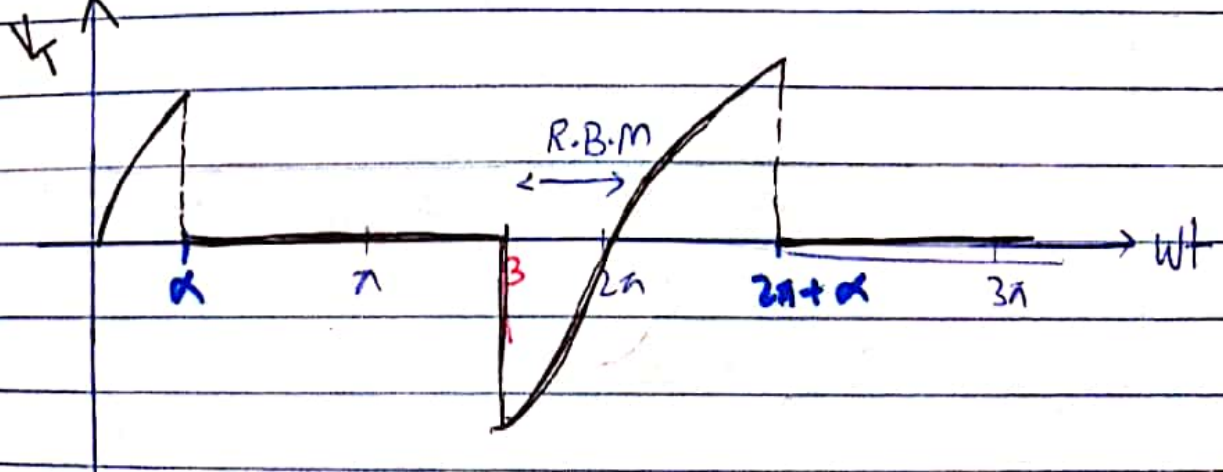
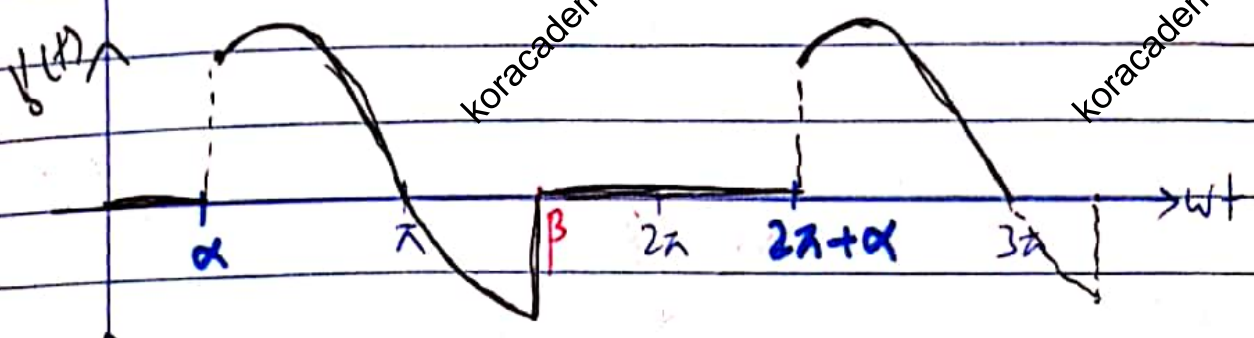
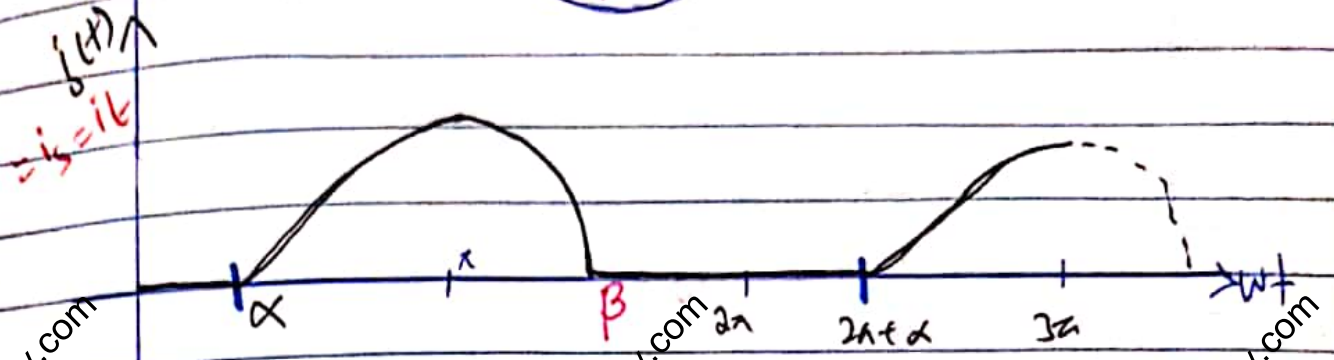
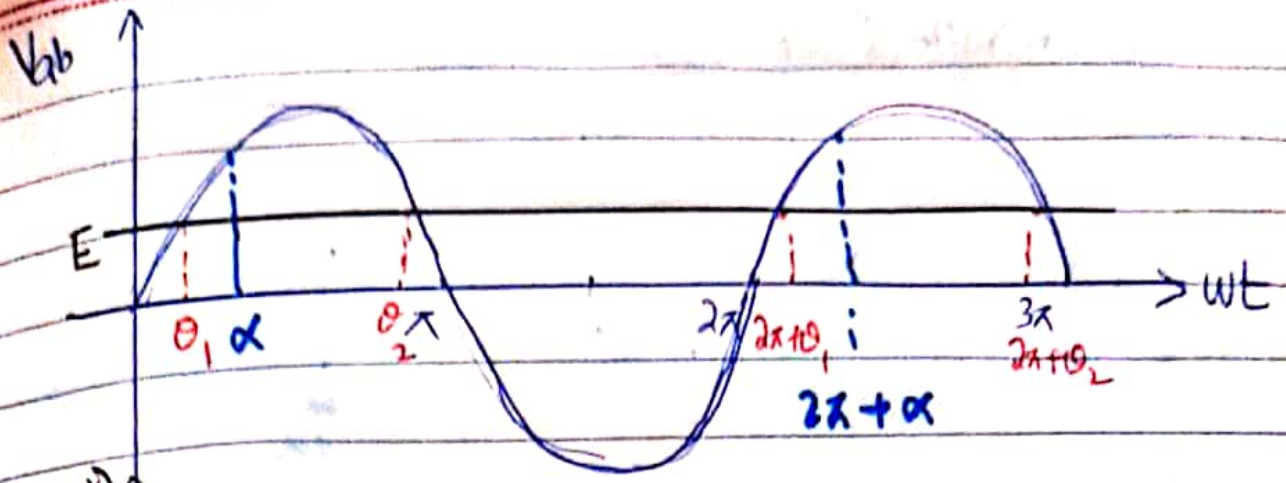
(1) ON $\rightarrow V_T = 0, i_T = i_o$

(2) OFF

(1) ON $\rightarrow V_T = 0, i_T = i_o \rightarrow \text{exists}, V_o = V_{ab} = V_m \sin \omega t$

(2) OFF $\rightarrow i_T = 0, V_o = 0, V_T = V_m \sin \omega t$

$$V_m \sin \omega t = V_T + V_o$$



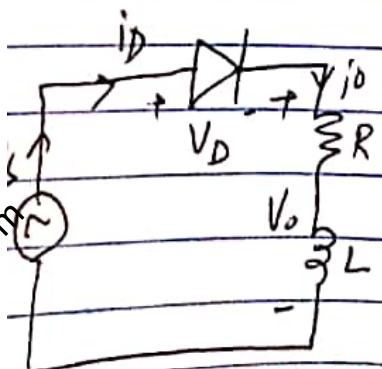
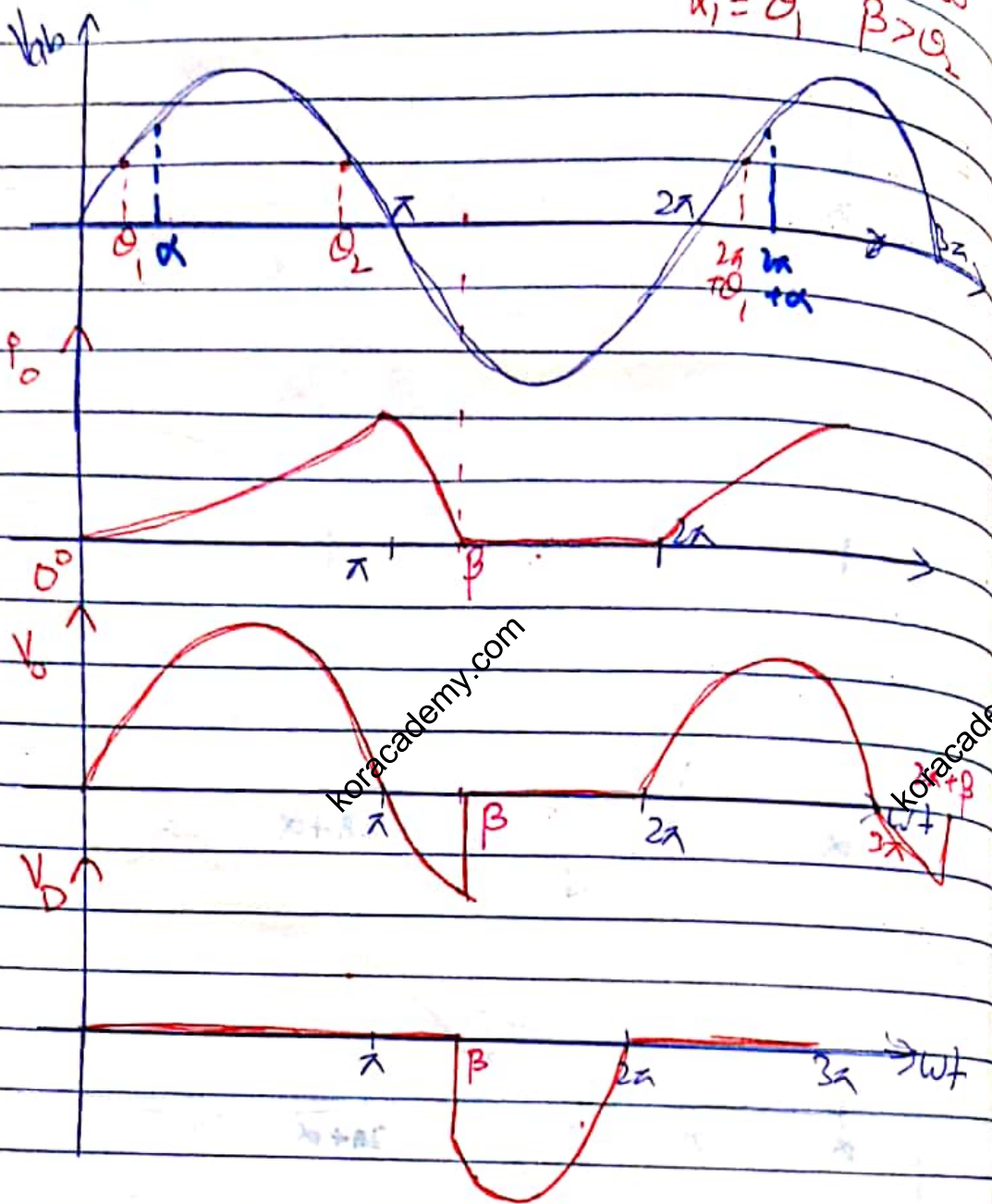
$\beta \quad \theta_1 = 0^\circ \quad \theta_2 = 180^\circ$

$\alpha, \beta > 180^\circ$

Date: / /

(ii) Uncontrolled RL Load

$\theta_1 = 0^\circ$ $\theta_2 = 180^\circ$
 $\alpha_1 = \theta_1$ $\beta > \theta_2$



When
 D is ON $\rightarrow V_D = 0$ $i_o = \frac{e \sin \omega t}{R}$
 D is OFF $\rightarrow i_o = 0$ $V_D = 0$
 $V_D = V_m \sin \omega t$

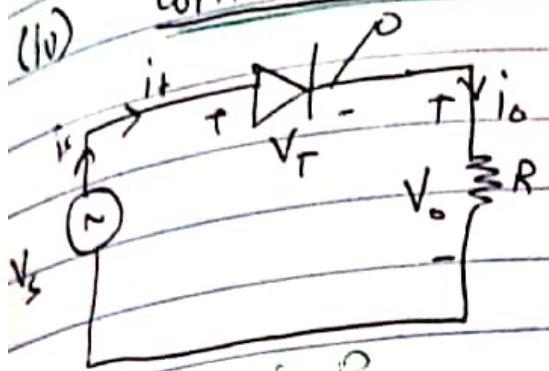
$\theta_1 = 0^\circ$ as $\sin^{-1}\left(\frac{E}{V_m}\right)$ $\theta_2 = 180^\circ$

$\alpha = \theta_1 = 0^\circ$ $\beta > \theta_2 \Rightarrow \beta > 180^\circ$

Controlled R Load

$\theta_1 = 0^\circ$ $\theta_2 = 180^\circ$

α $\beta = 180^\circ = \theta_2$

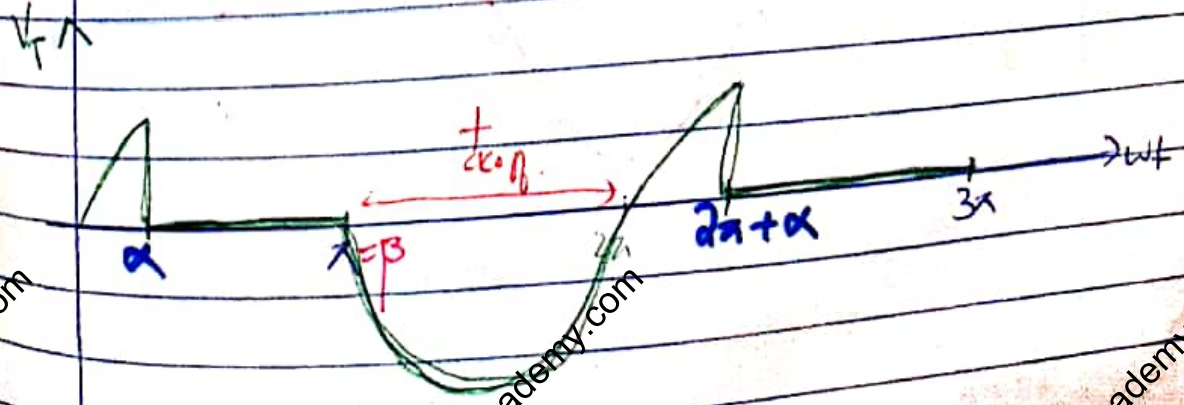
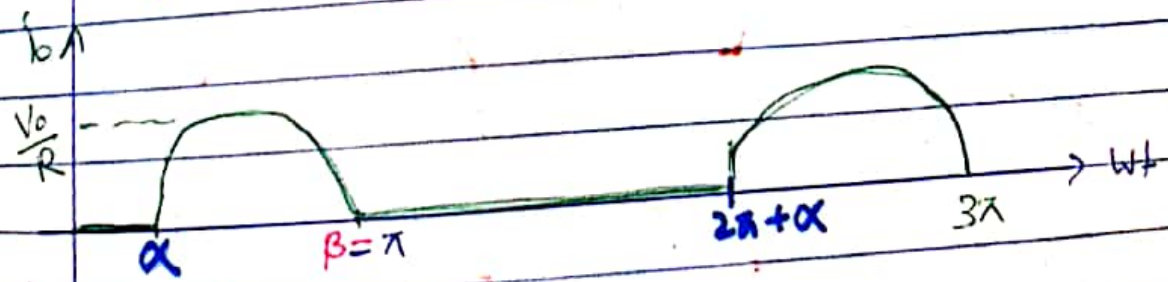
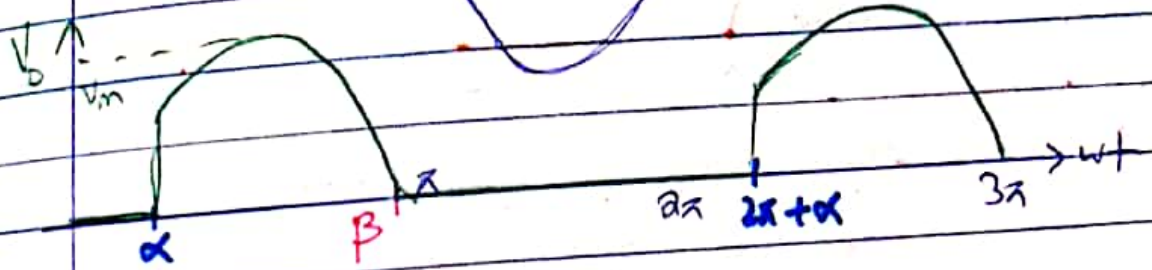
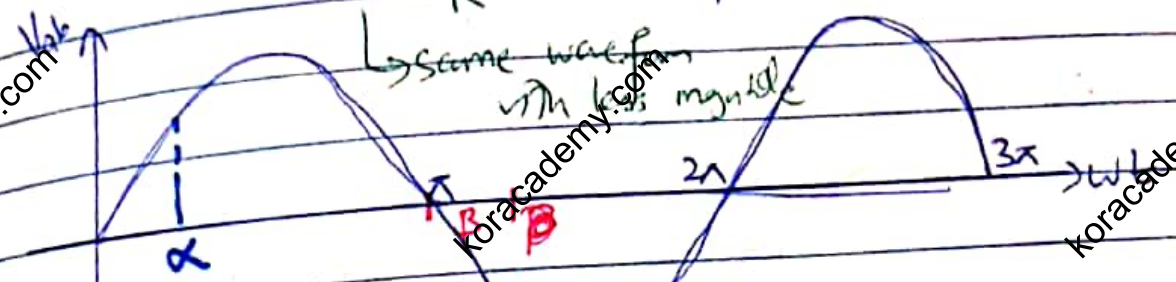


SCR = ON
 $\hookrightarrow V_T = 0V$ i_o exists
 $V_o = V_{as} = V_m \sin \omega t$

SCR = OFF
 $\hookrightarrow i_o = 0$ $V_o = 0$
 $\hookrightarrow V_T = V_m \sin \omega t$

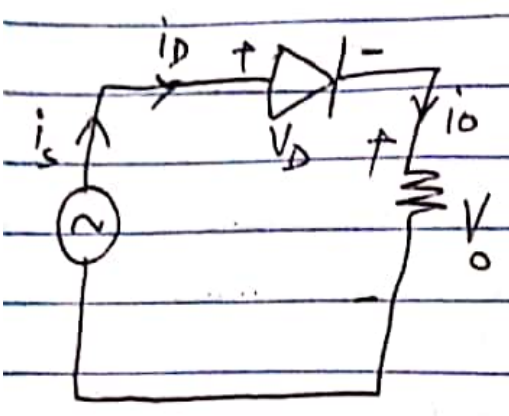
$V_o = i_o R$

$i_o = \frac{V_o}{R}$



Date: / /

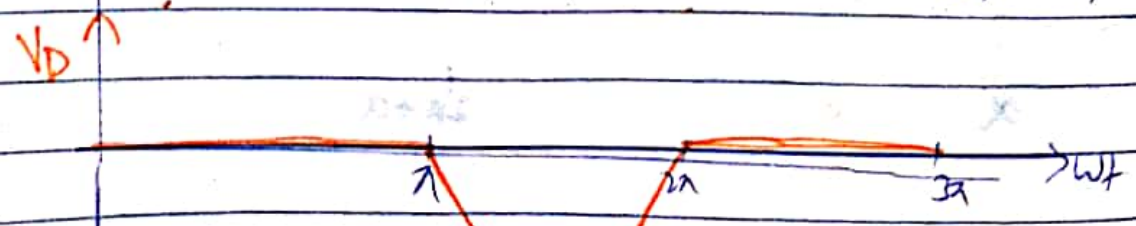
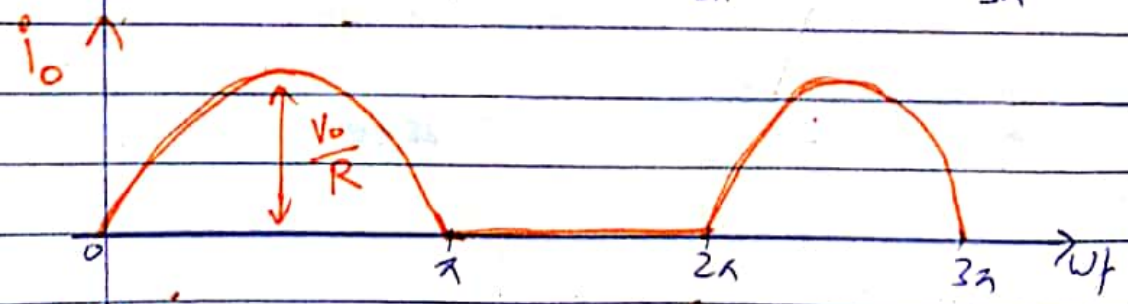
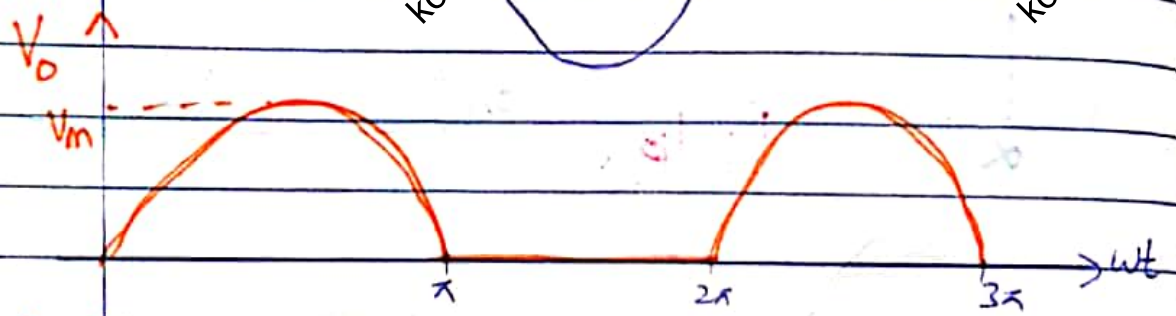
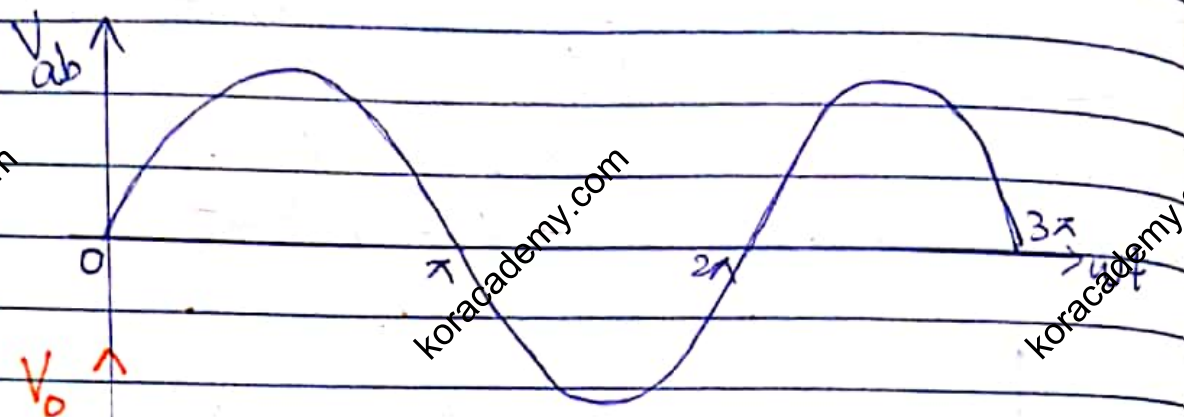
(iii) Uncontrolled R Load $\alpha = \theta_1 = 0^\circ$ $\beta = \theta_2 = \pi$



$D \rightarrow ON$
 $\rightarrow V_D = 0$ i_o exists
 \rightarrow follows voltage

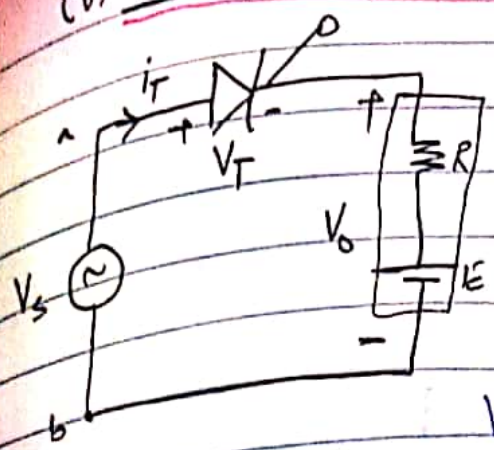
$D \rightarrow OFF$
 $\rightarrow i_o = 0A$ $V_o = 0$

$V_D = V_m \sin \omega t$



(v) RE load Controlled Rectifier

$\theta_1 \neq 0 \quad \theta_2 = 180^\circ - \theta_1$
 $\alpha, \beta = \theta_2 = 180^\circ - \theta_1$



SCR = ON

$\rightarrow V_T = 0 \quad I_o \text{ exists}$

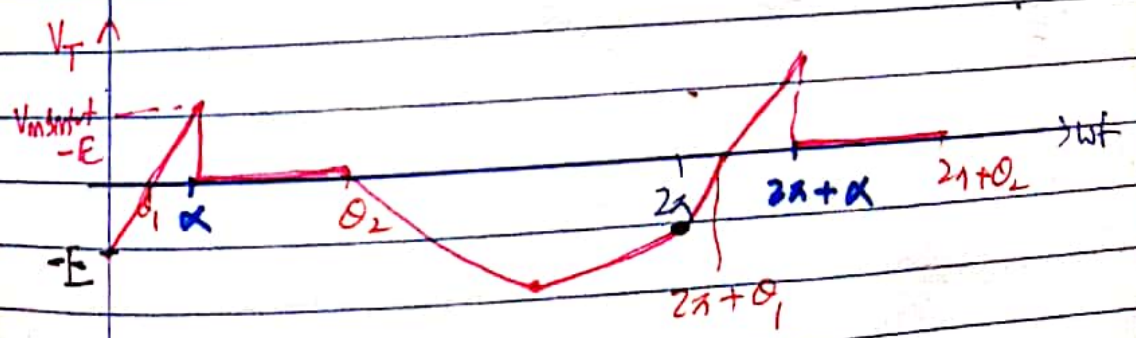
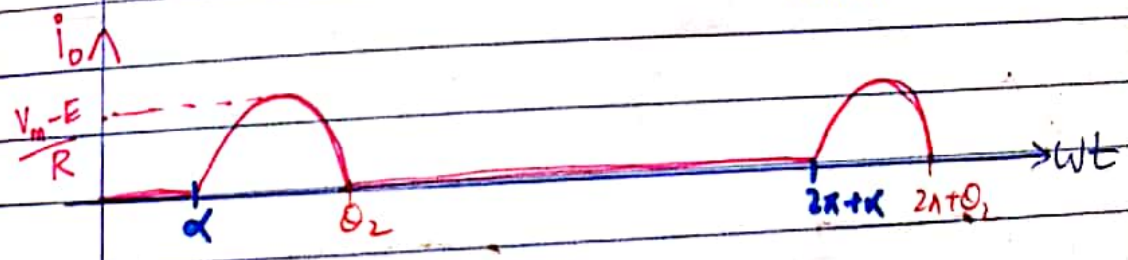
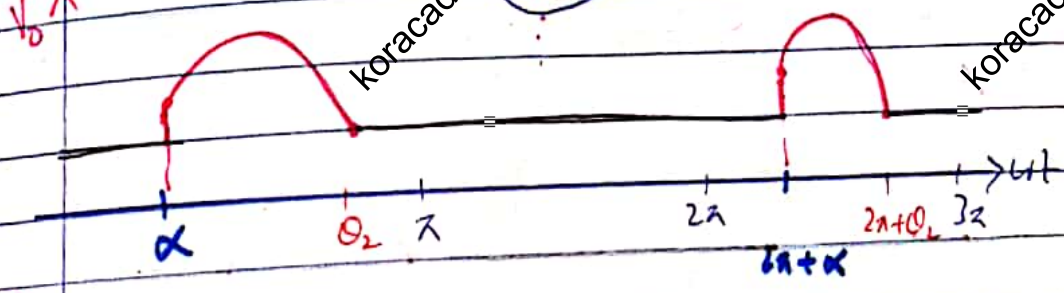
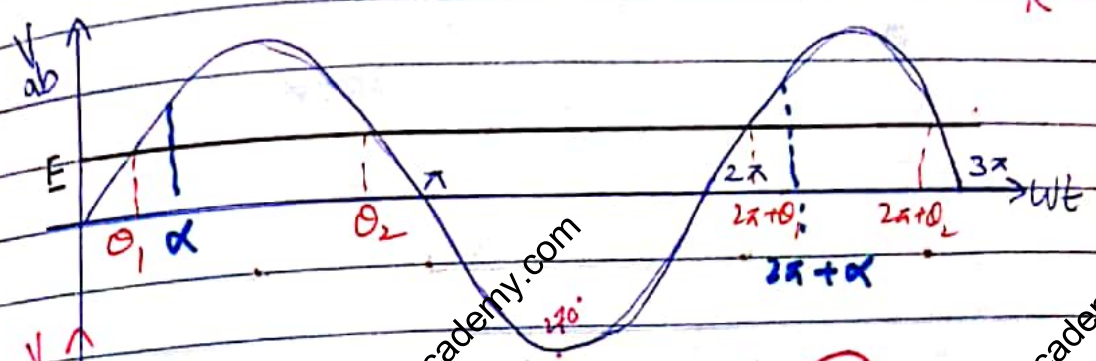
$I_o = \frac{V_o - E}{R}$

SCR = OFF

$\rightarrow I_o = 0 \quad V_o = E$

$V_T = V_m \sin \omega t - E$

$I_o = \frac{V_m \sin \omega t - E}{R}$



At $\theta_1 \Rightarrow V_T = 0$
 At $\omega t = 0 \Rightarrow V_T = -E$
 At $\theta_2 \Rightarrow V_T = 0$
 At $2\pi \Rightarrow V_T = -E$

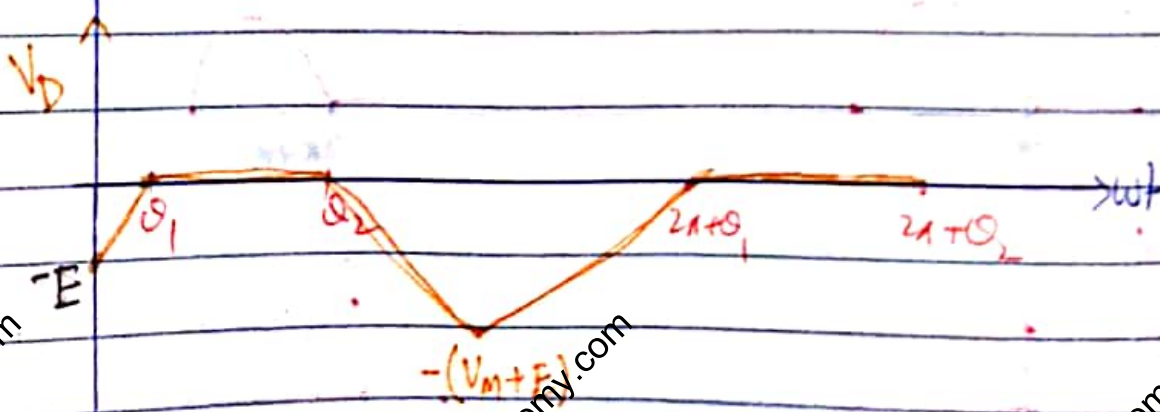
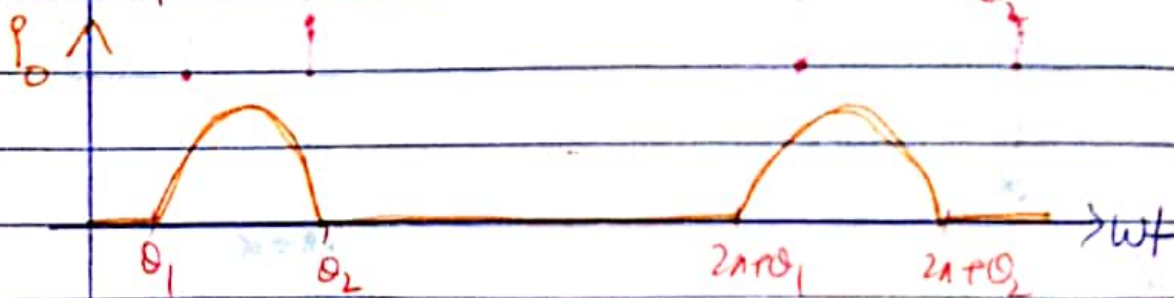
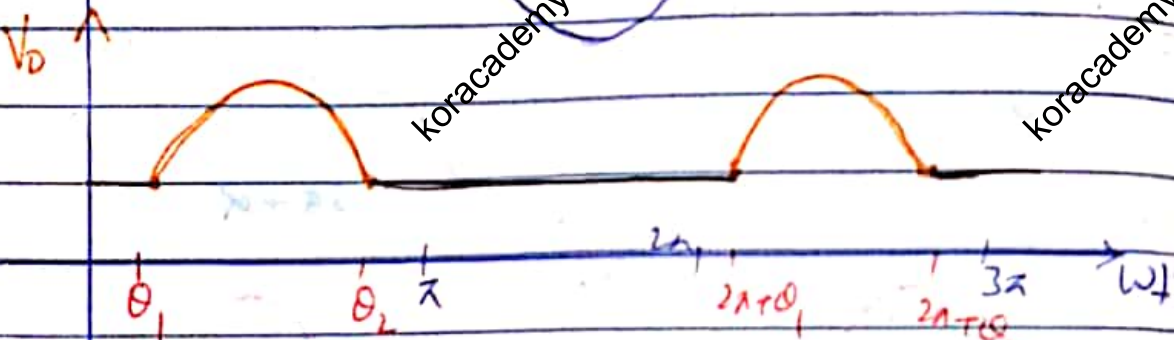
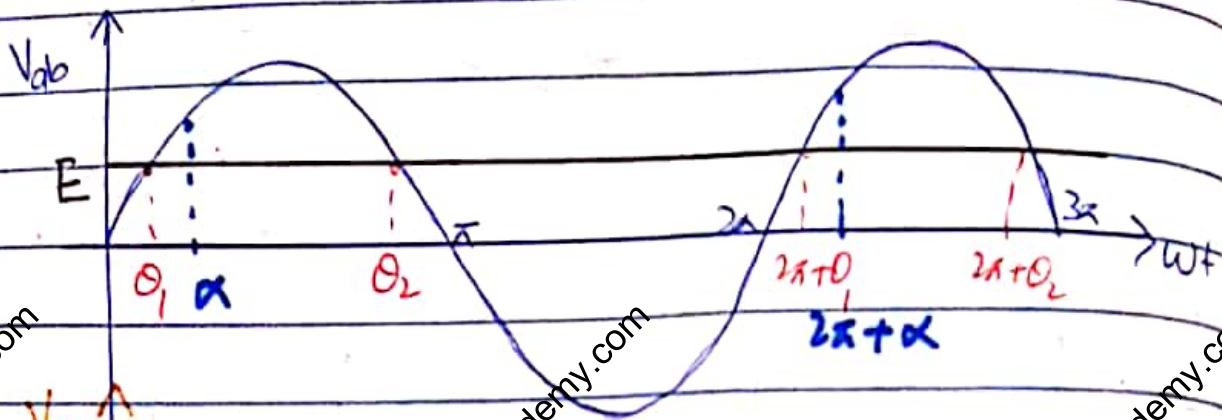
At $\omega t = 270^\circ \Rightarrow V_T = -(V_m + E)$

3 Babar Register

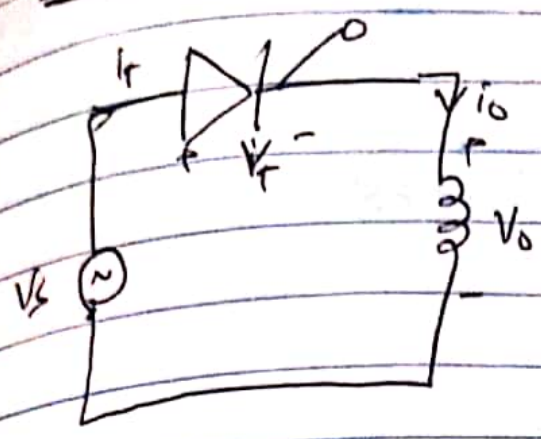
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(vi) Uncontrolled with RE load

$$\theta_1 \neq 0 \quad \theta_2 = 180^\circ - \theta_1$$
$$\alpha = \theta_1 \neq 0 \quad \beta = \theta_2$$



L Load controlled.



$$V_{ab} = V_m \sin \omega t$$

$$0 < \omega t < \alpha$$

↳ F.b.M

↳ b/c no firing angle

↳ SCR = OFF

$$\rightarrow i_o = 0A$$

$$\rightarrow V_o = 0V$$

$$\omega t > \alpha$$

↳ SCR = ON $\rightarrow V_T = 0 \rightarrow V_o = V_s = V_m \sin \omega t$

$$A \quad V_o = L \frac{di}{dt} \quad \rightarrow \quad L \frac{di_o}{dt} = V_m \sin \omega t$$

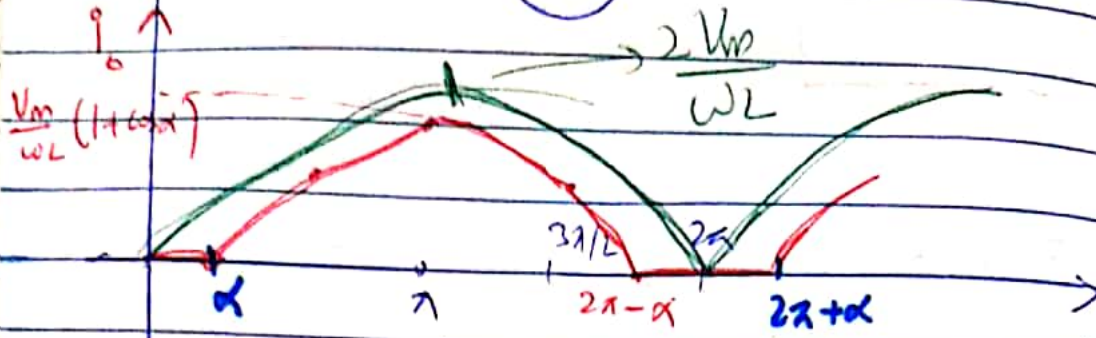
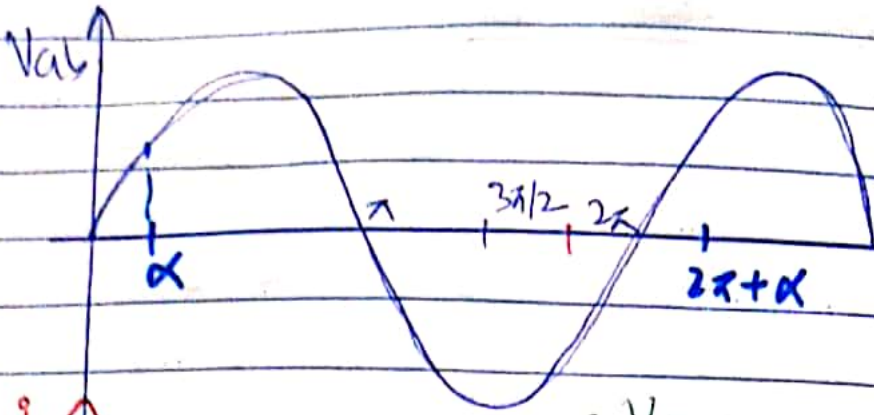
Turn OFF of any device is decided by current. α/ω $\int_{\alpha/\omega}^t di_o = \int_{\alpha/\omega}^t \frac{V_m}{L} \sin \omega t dt$

$$i_o(t) - i_o(\alpha) = \frac{V_m}{\omega L} \left[-\cos \omega t \right]_{\alpha/\omega}^t$$

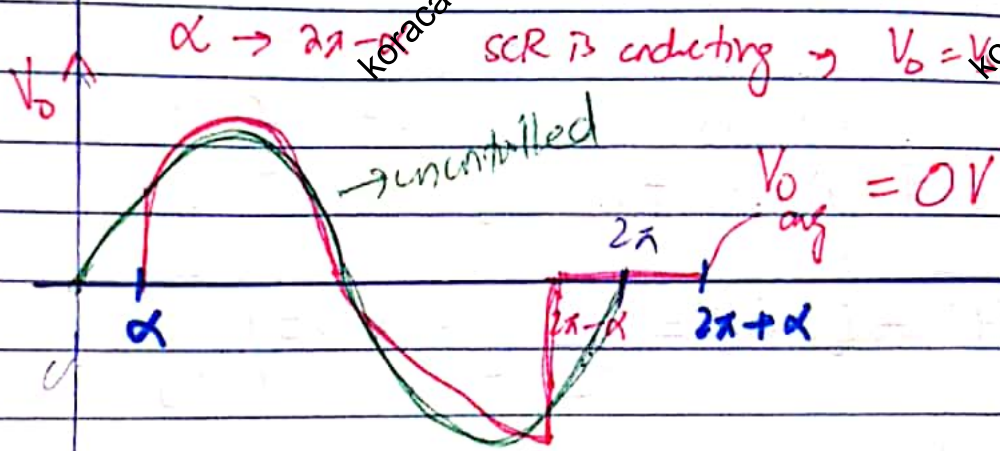
At instant firing angle point current is zero.

$$i_o(t) = \frac{V_m}{\omega L} \left[\cos \alpha - \cos \omega t \right]$$

if uncontrolled $\alpha = 0^\circ$

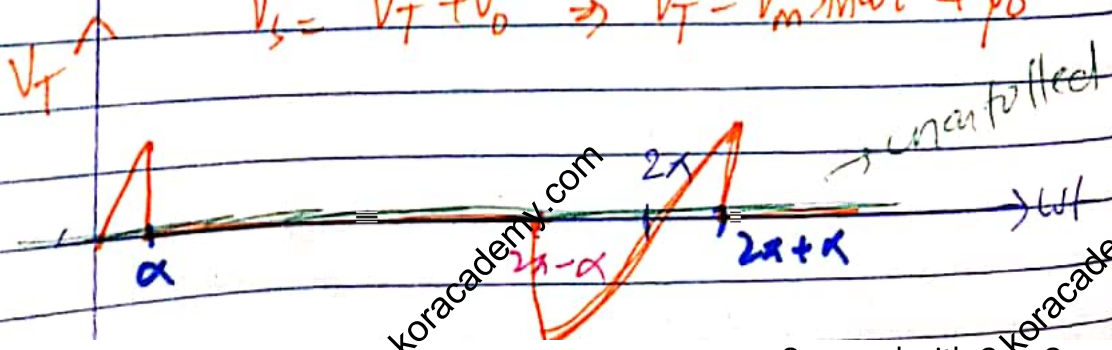


$\beta = 2\pi - \alpha$



for V_T
 α to $2\pi - \alpha$ SCR is ON
 $\hookrightarrow V_T = 0$ here

SCR is off $V_T = ?$
 $V_s = V_T + V_o \Rightarrow V_T = V_m \sin \omega t + V_o$



$$I_o(\text{avg}) = \frac{1}{2\pi} \int_{\alpha}^{2\pi - \alpha} i_o(t) d\omega t$$

If uncontrolled $\alpha = 0^\circ$

$$i_o(t) = \frac{V_m}{\omega L} (\cos 0^\circ - \cos \omega t)$$

$$i_o(t) = \frac{V_m}{\omega L} [1 - \cos \omega t]$$

$$\beta = 2\pi - \alpha = 2\pi - 0^\circ$$

$$\Rightarrow \beta = 2\pi \text{ rad}$$

$$V_D = 0$$

$$V_{\text{avg}} = 0$$

Max energy stored ?

$$= \frac{1}{2} L I^2$$


for diode put $i = \frac{2V_m}{\omega L}$


for SCR put $i = \frac{V_m}{\omega L} (1 + \cos \alpha)$


$$\text{Form factor} = \frac{V_{\text{rms}}}{V_{\text{avg}}}$$

The form factor of a pure sine wave is 1.11

$$P_{\text{input}} = P_{\text{output}}$$

—  — $P = I_{\text{rms}}^2 R \rightarrow \text{dissipated}$

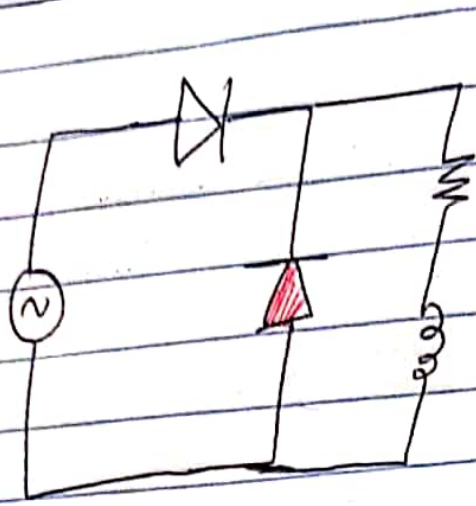
—  — $P = E \times I_{\text{avg}} \rightarrow \text{stored / delivered}$

—  — $P = \text{Watt}$

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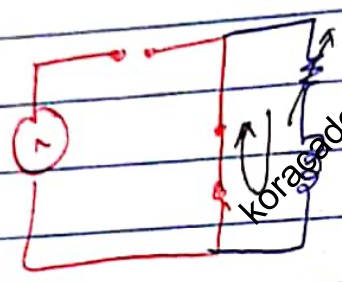
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Half Wave Uncontrolled Rectifier with RL Load and free wheeling diode



0 to π
 $V_o = V_s = V_m \sin \omega t$

After π
 F.W.D will be active i.e. shorted

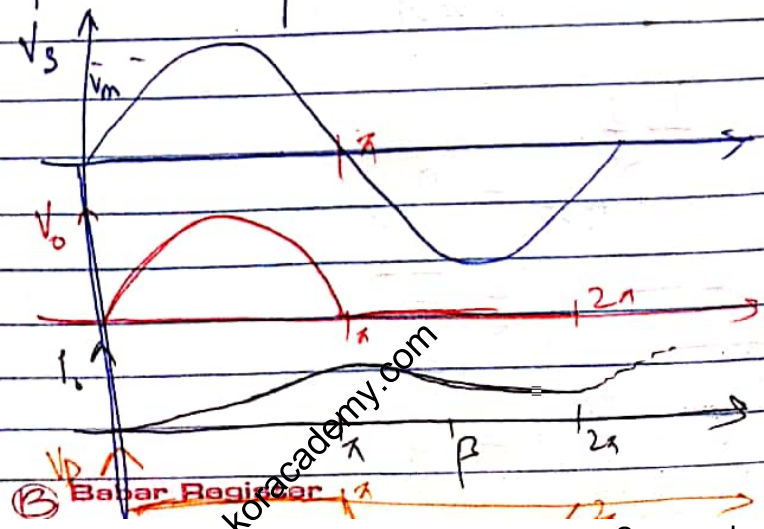


The energy across inductor will discharge across resistor.

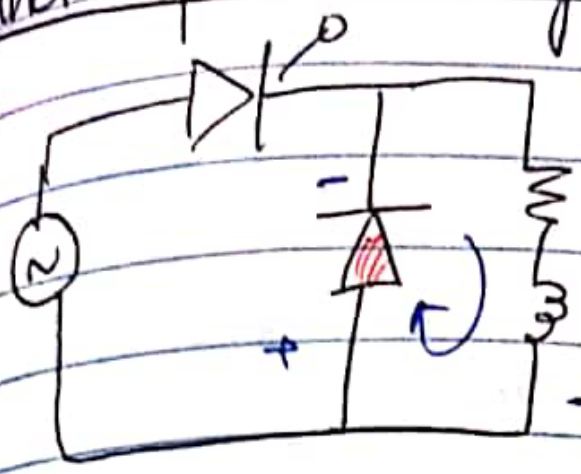
$$i_o(t) = I_o e^{-t/\tau} \quad \tau = L/R$$

With F.W.D all energy of the inductor is dissipated across the resistor and nothing is supplied back to the source.

After 2π repeats.



Half Wave Controlled rectifier with RL load and free wheeling diode



α to π
 Thyristor conducts
 o/p V is equal to i/p voltage

After π F.W.D conducts \rightarrow shunted

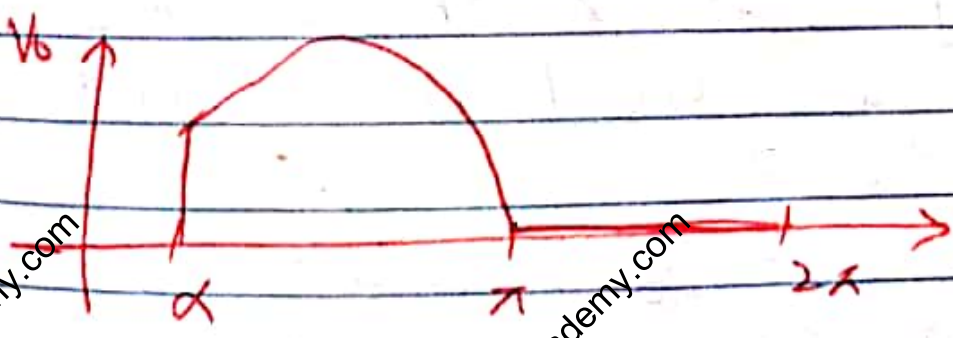
KVL $V_D + V_o = 0$
 $V_D = -V_o$

0 to π inductor charges.

π to 2π " discharges.

\rightarrow so I_o is continuous.

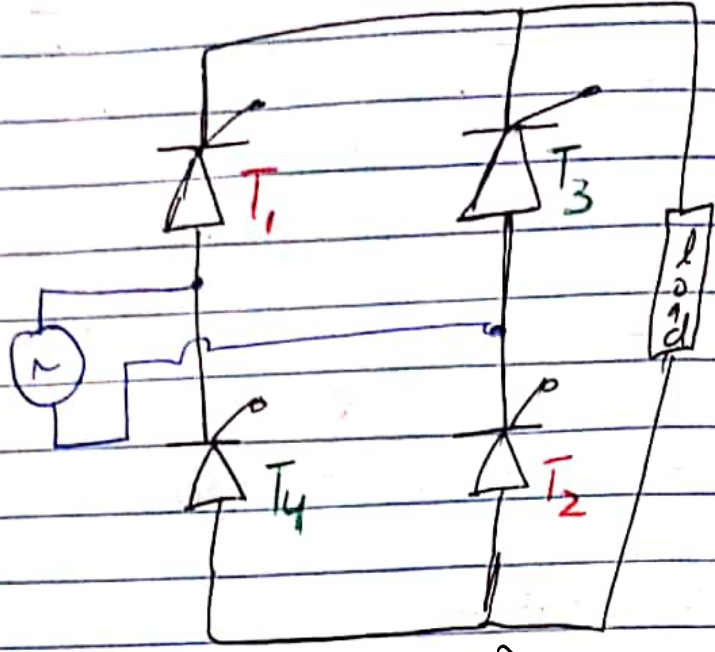
$I_{rms\ source} \neq I_{rms\ load}$ only in this case.



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Single Phase

Full Wave uncontrolled Bridge Rectifier



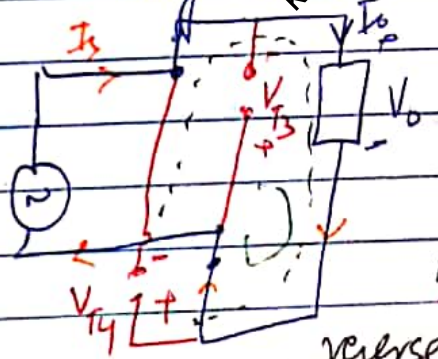
Assuming
 $I_o = \text{constant}$

PLE $\approx RL$

Highly inductive load.

$$V_{\text{avg}} = V_m \sin \omega t$$

At $\omega t = \alpha$ triggering T_1 and T_2
 so they conduct from α to $\pi + \alpha$



$$V_o = V_s = V_m \sin \omega t$$

$$V_o = V_{BA}$$

After π , thyristors are reverse biased so they should stop conduction?

We assume that I_o is constant for turning OFF
 $I_o \leq I_H$

At $\pi + \alpha$ we trigger T_3 and T_4
 so T_1 and T_2 go to reverse mode and stop conducting.

As T_3 and T_4 are not triggered from α to $\pi + \alpha$, so they are open circuit in this region.

$$\text{KVL } V_{T4} + V_o = 0$$

$$V_{T4} = -V_o \quad (\alpha \text{ to } \alpha + \alpha)$$

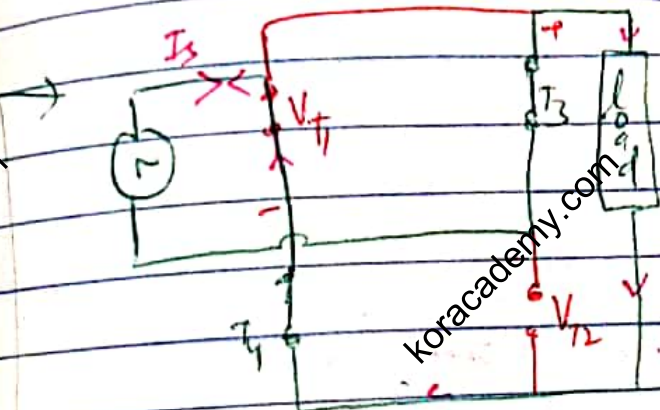
Similarly in the inner loop

$$V_{T3} + V_o = 0$$

$$V_{T3} = -V_o \quad (\alpha \text{ to } \alpha + \alpha)$$

When T_1 and T_2 are conducting, then

$$V_{T3T4} = -V_o$$



$$V_o + V_{ab} = 0$$

$$V_o = -V_{ab} = V_{ba}$$

$$V_{T1T2} = -V_o$$

T_1 , and T_2 stops conducting.

0 to α T_3T_4 is conducting

↳ load current is constant

↳ At any time, any two thyristors must be conducting.

Source current

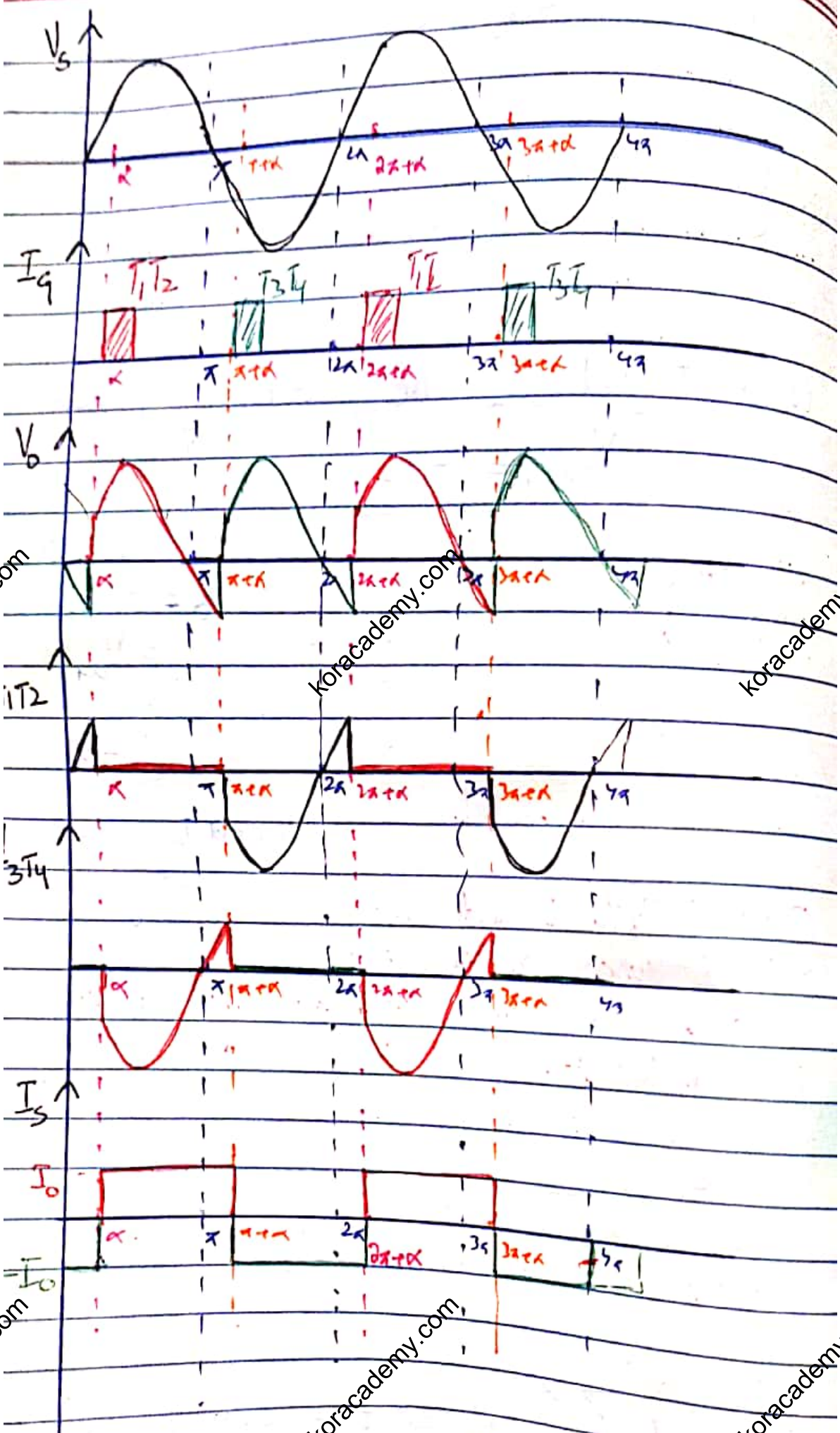
$$\alpha \text{ to } \alpha + \alpha \Rightarrow I_o = I_s$$

$$\alpha + \alpha \text{ to } 2\alpha + \alpha \Rightarrow I_s = -I_o$$

Parameters

$$V_{avg} = \frac{1}{\pi} \int_{\alpha}^{\pi + \alpha} V_m \sin \omega t \, d\omega t = \frac{2V_m}{\pi} \cos \alpha$$

Date: / /



$$t_c = \frac{\pi - \alpha}{\omega}$$

Thyristor current.

Each Thyristor is conducting for a period of α .

$$I_{avg} = I_0 \left(\frac{\alpha}{2\pi} \right) = \frac{I_0}{2}$$

$$I_{rms} = I_0 \sqrt{\frac{\alpha}{2\pi}} = \frac{I_0}{\sqrt{2}}$$

$$V_0 = \frac{2V_m \cos \alpha}{\pi}$$

① $\alpha < 90^\circ$, $V_0 > 0$, $I_0 > 0$

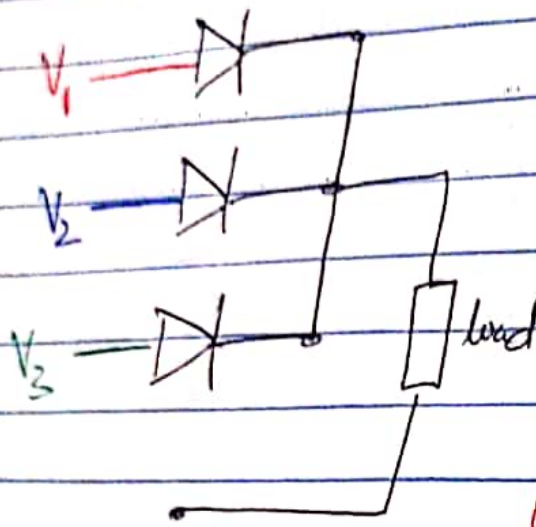
$P_0 > 0 \rightarrow$ power is transferred from source to load.

② $\alpha > 90^\circ$, $V_0 < 0$, $I_0 < 0$

$P_0 < 0 \rightarrow$ power is transferred from load to source.

\rightarrow inverter

3 phase Half Wave Uncontrolled Rectifier



From $\omega t = 30^\circ$ to 150°
 $V_1 > V_2$ and V_3

D_1 will conduct

$\Rightarrow V_o = V_1$

$\omega t = 150^\circ$ to 270°

$V_2 > V_1$ and V_3

D_2 will conduct

$V_o = V_2$

$270^\circ - 360^\circ$

$V_3 > V_1$ and V_2

$\Rightarrow D_3$ will conduct

and will follow i/p voltage

For resistive load;

current follows the voltage waveform.

For inductive load, I_o is constant.

This is also known as 3 pulse converter.
 as we have 3 pulses in o/p waveform.

$f_o = 3f_s$

Each diode is conducting for 120° in each cycle.

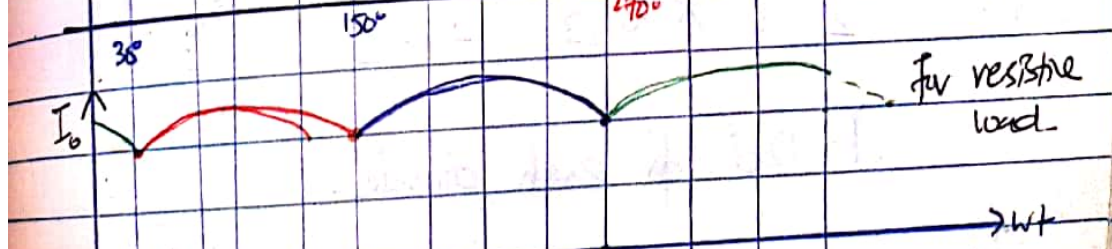
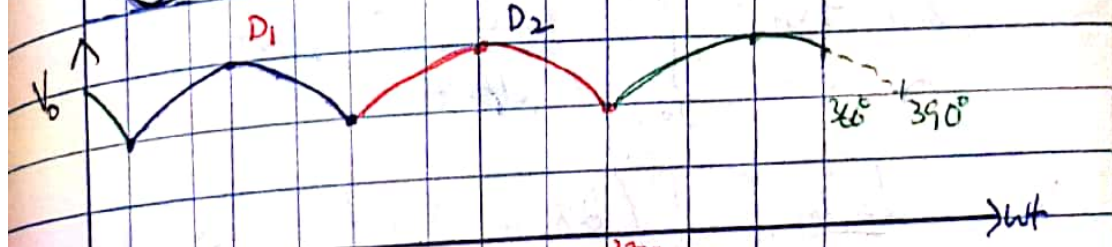
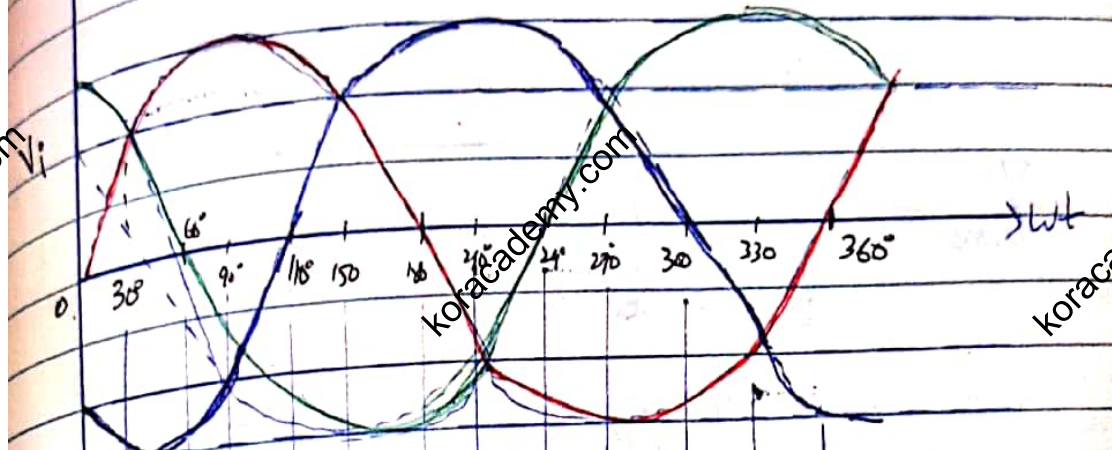
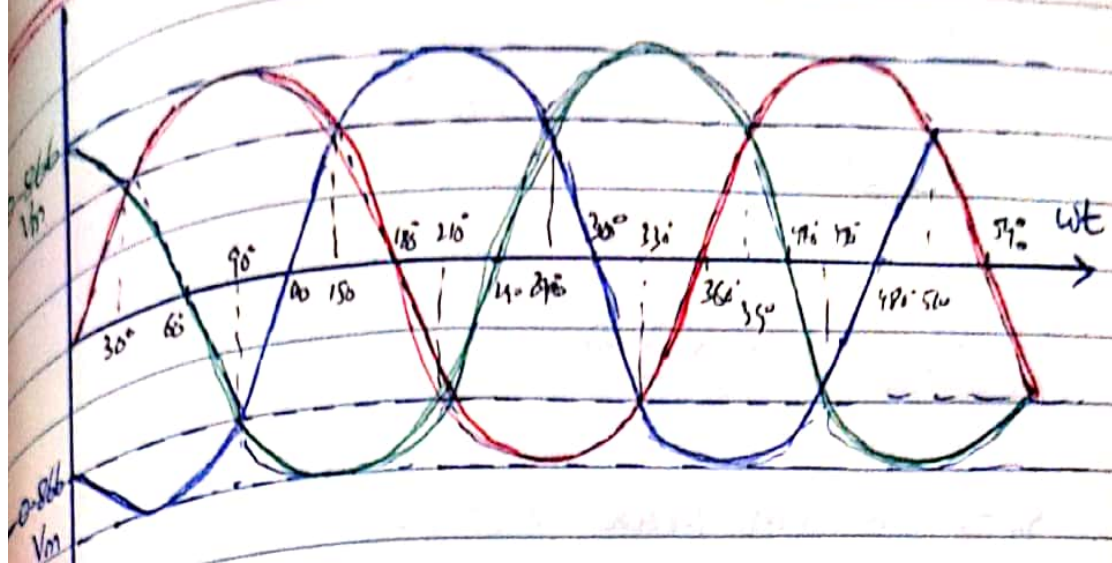
Date: _____

$$V_A = V_m \sin \omega t$$

$$V_B = V_m \sin(\omega t - 120^\circ)$$

$$V_C = V_m \sin(\omega t + 120^\circ)$$

Day _____



$$V_{avg} = \frac{1}{120^\circ} \int_{30^\circ}^{150^\circ} V_m \sin \omega t \, d\omega t$$

$$= \frac{3}{2\pi} V_m \left[-\cos \omega t \right]_{30^\circ}^{150^\circ}$$

$$V_{avg} = \frac{3\sqrt{3} V_m}{2\pi}$$

$V_m \rightarrow$ maximum phase voltage

$$V_m = \sqrt{\frac{2}{3}} V_e$$

$$V_{orms} = \sqrt{\frac{1}{2\pi} \int_{30^\circ}^{150^\circ} V_m^2 \sin^2 \omega t \, d\omega t}$$

$$= \sqrt{\frac{3V_m^2}{2\pi} \int_{30^\circ}^{150^\circ} \frac{1 - \cos 2\omega t}{2} \, d\omega t}$$

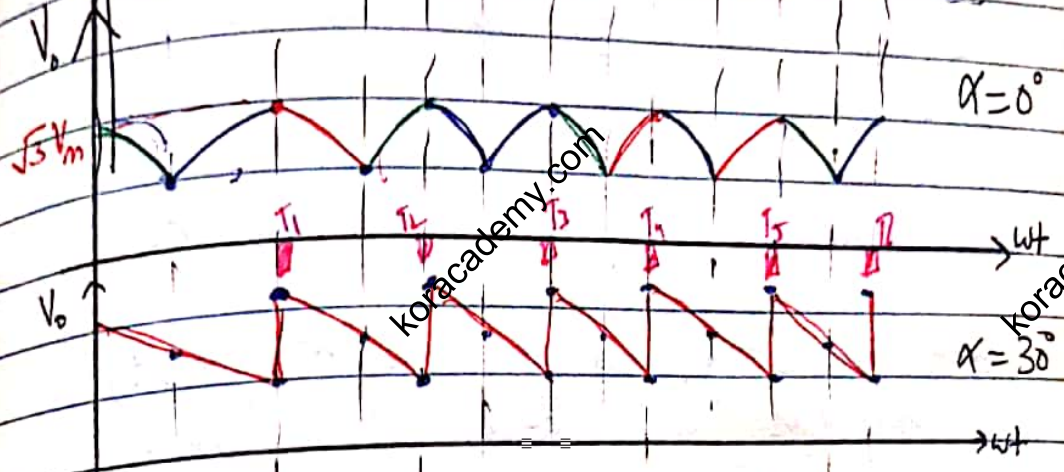
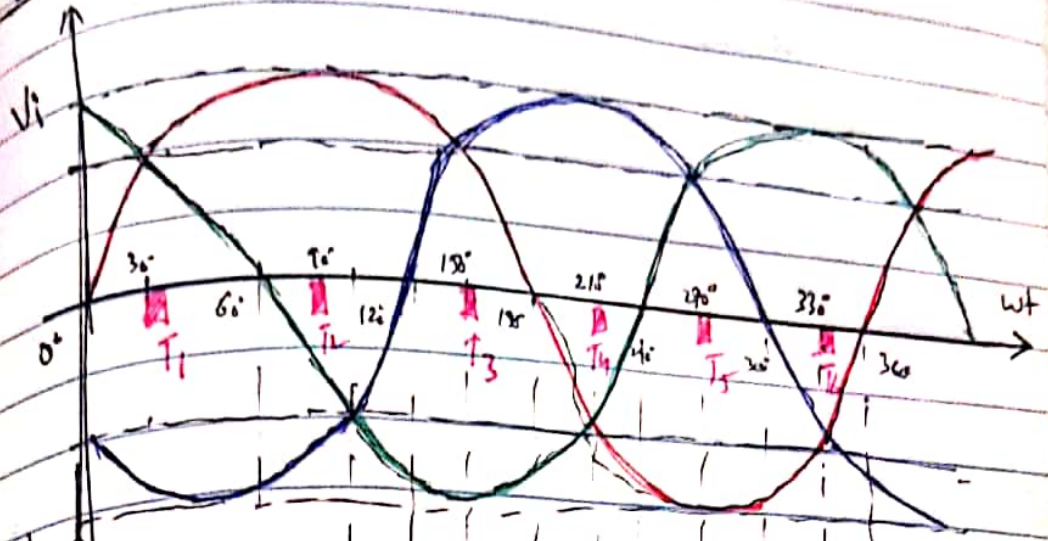
$$V_{orms} = \frac{\sqrt{3} V_m}{2} \left[\frac{1}{\pi} \left(\frac{2\pi}{3} + \frac{\sqrt{3}}{2} \right) \right]^{1/2}$$

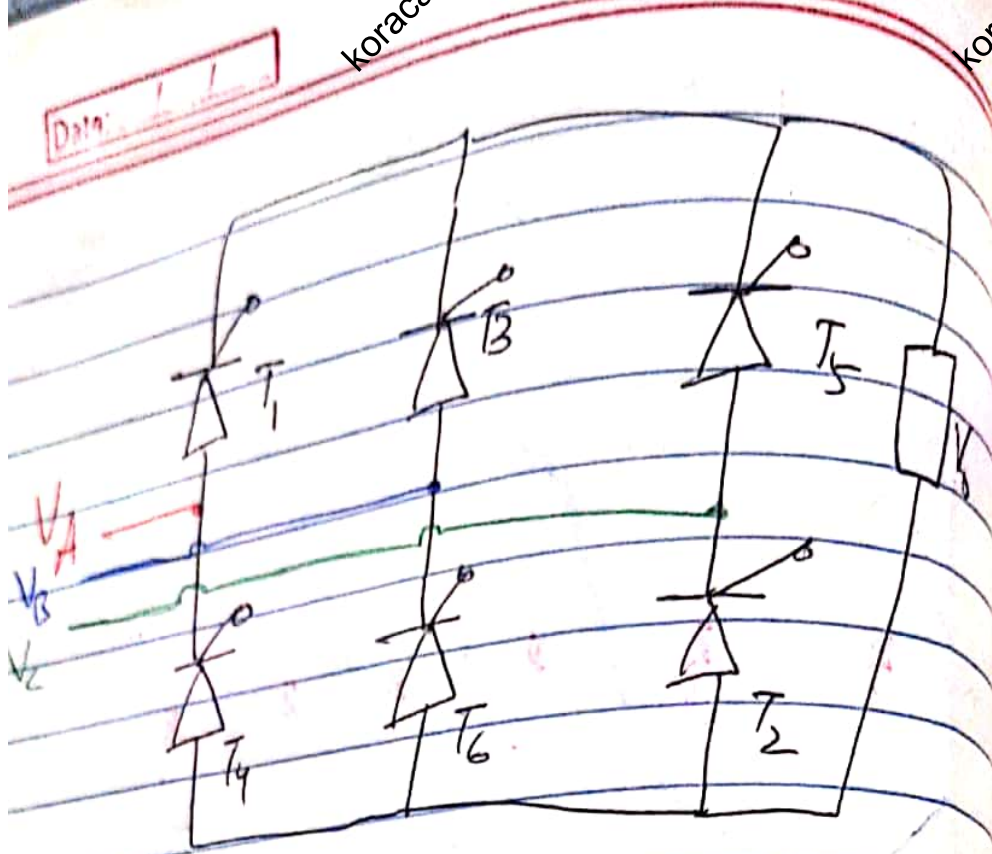
$\gamma = 120^\circ$ for each diode.

$$I_D(avg) = I_o \left(\frac{120}{360} \right) = I_o/3$$

$$I_{D,rms} = I_o \sqrt{\frac{120}{360}} = I_o/\sqrt{3}$$

Three Phase Controlled Full Wave Bridge Rectifier





$$V_A = V_m \sin \omega t \quad V_B = V_m \sin(\omega t - 120^\circ)$$

$$V_C = V_m \sin(\omega t + 120^\circ)$$

Each thyristor is triggered at 60° duration.

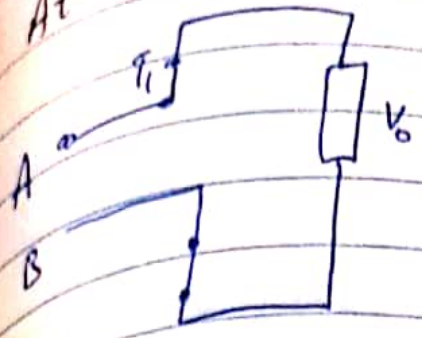
When ip voltage is given to this circuit, two thyristors will conduct at a time.

The sequence is like this;

$$T_6 T_1 \rightarrow T_1 T_2, T_2 T_3 \rightarrow T_3 T_4 \rightarrow T_4 T_5 \rightarrow T_5 T_6$$

$\alpha = 0^\circ$
~~Suppose that~~ we trigger T_1 at $\alpha = 30^\circ$
 so means T_2 will be triggered at 90°
 T_3 at 150° , T_4 at 210° , T_5 at 270°
 and T_6 at 330°
 $\rightarrow \Rightarrow \omega t = 30^\circ$

At $\omega t = 30^\circ \rightarrow T_6$ and T_1 are conducting



$$V_o = V_{AB} = V_A - V_B$$

Put $\omega t = 30^\circ$

$$V_o = V_m \sin 30^\circ - V_m \sin 90^\circ$$

$$V_o = 1.5 V_m$$

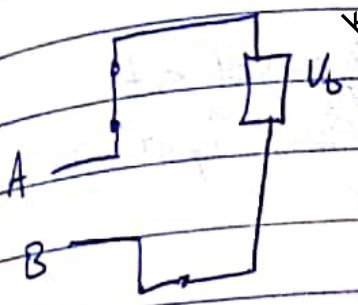
At $\omega t = 60^\circ \rightarrow T_6, T_1$ will conduct.

$$V_o = V_m \sin 60^\circ - V_m \sin(-60^\circ)$$

$$V_o = \sqrt{3} V_m$$

At $\omega t = 90^\circ$.

T_1 and T_2 will conduct.



$$V_o = V_{AC} = V_A - V_C$$

Put $\omega t = 90^\circ$

$$V_m \sin 90^\circ - V_m \sin(90^\circ - 240^\circ)$$

$$V_o = 1.5 V_m$$

The o/p voltage represents line to line voltage.

At $\omega t = 120^\circ$ T_2 and T_1 conduct.

$$V_o = V_A - V_C$$

$$V_m \sin(120^\circ) - V_m \sin(-120^\circ)$$

$$V_o = \sqrt{3} V_m$$

At $\omega t = 150^\circ$ T_2, T_3 conducting

$$V_o = V_B - V_C = V_{BC}$$

At $\omega t = 150^\circ$

$$V_o = V_m \sin(150^\circ - 120^\circ) - V_m \sin(150^\circ - 240^\circ)$$

$$\Rightarrow V_o = 1.5 V_m$$

In this way repeat.

Each thyristor conducts for 120° .

Same current we will get for 240°

The second sketch is for $\alpha = 30^\circ$

which means that T_1 is triggered at $\omega t = 60^\circ$, T_2 at 120° , T_3 at 180° , T_4 at 240° , T_5 at 300° and T_6 at 360°

At $\omega t = 60^\circ$ T_6 and T_1 will conduct.

$$V_o = V_{AB} = V_A - V_B$$

$$V_o = \sqrt{3} V_m$$

At $\omega t = 90^\circ$

$$V_o = V_{AD} = V_A - V_B$$

$$V_o = 1.5 V_m$$

At $\omega t = 120^\circ$ T_1 and T_2

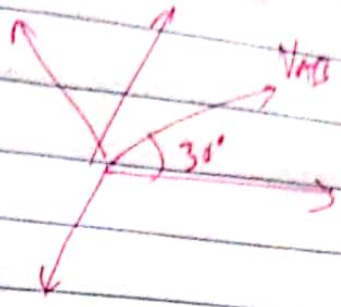
$$V_o = V_A - V_C$$

$$V_o = \sqrt{3} V_m$$

$f \omega \omega t = 120^\circ$

$$V_0 = A_{AB} = V_A - V_B = \frac{\sqrt{3}}{2} V_m$$

$$V_{AB} = V_m \sin(\omega t + 30^\circ)$$



Chopper

chopper is nothing but a DC to DC converter.

D → duty cycle

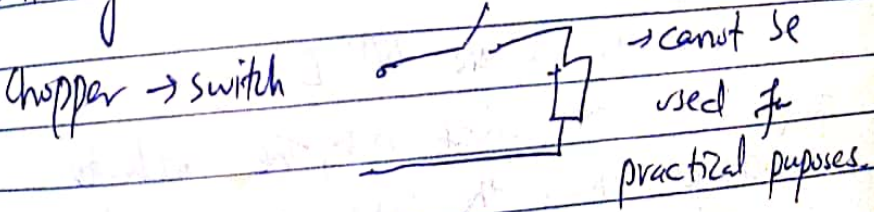
$$D = \frac{T_{ON}}{T}$$

$$T_{ON} = DT \quad T = T_{ON} + T_{OFF}$$

$$T_{OFF} = T - T_{ON} = T - DT$$

$$T_{OFF} = (1-D)T$$

Proper value of L and C, chode as switching element → converter.



Volt second balance

$$V_{L(ON)} T_{ON} + V_{L(OFF)} T_{OFF} = 0$$

$$V_{avg} = 0$$

Date: / /

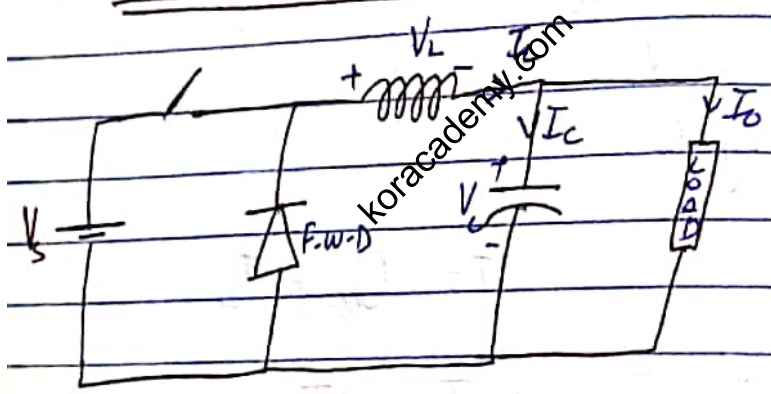
Ampere Second Balance.

$$I_{c (avg)} T_{(on)} + I_{c (OFF)} T_{(OFF)} = 0$$

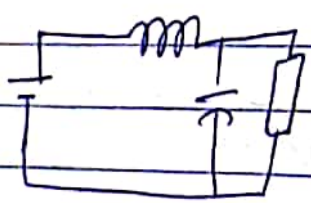
$$I_{c (avg)} = OFF$$

In all converters we will assume that load current I_o is constant.
So we will talk about continuous conduction mode only.

Buck Converter.



When switch is closed at $t=0$.

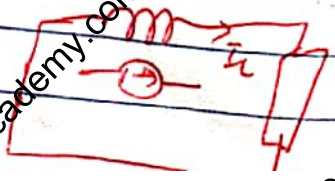


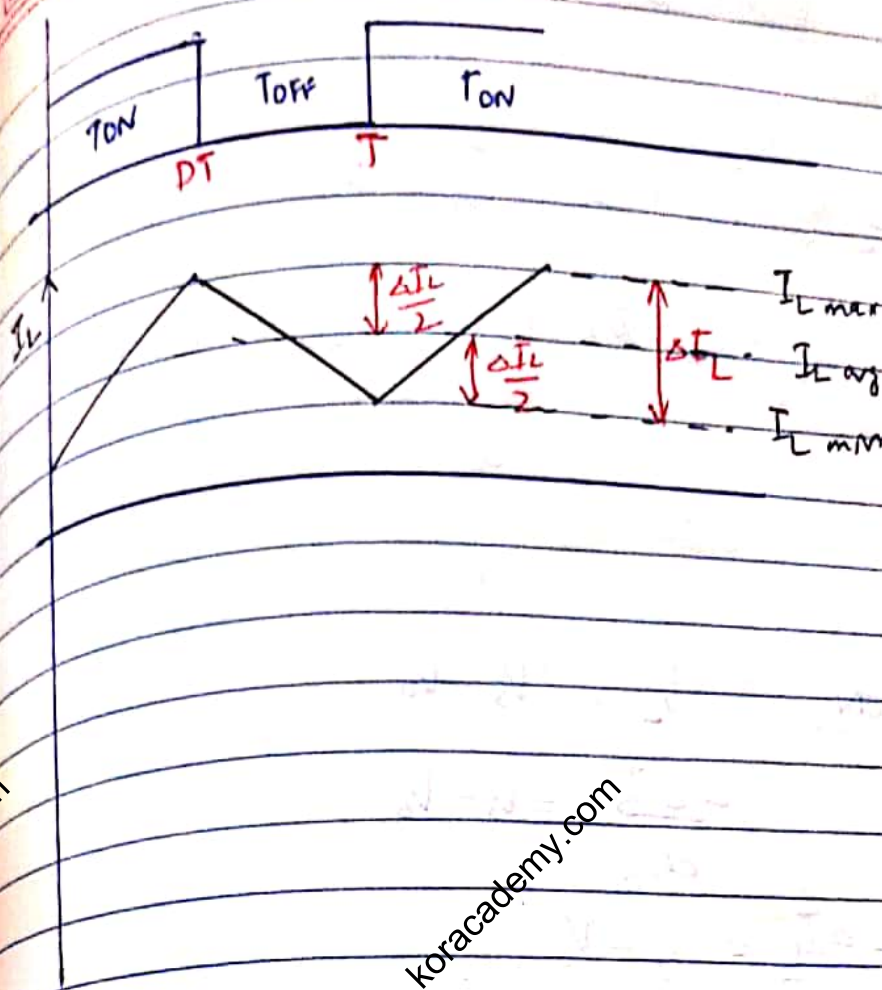
Inductor will charge until the switch is ON (closed).

Let the switch is ON till DT_o .

If you open the switch now, the inductor discharges through the load as current free wheels through the diode.

- The inductor acts as a current source here.





Switch if ON

$$V_{L(ON)} = V_s - V_o$$

$$I_{L(ON)} = I_L - I_o$$

Switch if OFF

$$V_{L(OFF)} + V_o = 0$$

$$V_{L(OFF)} = -V_o$$

$$I_{L(OFF)} = I_L - I_o$$

$$\Rightarrow V_{L(ON)} T_{ON} + V_{L(OFF)} T_{OFF} = 0$$

$$(V_s - V_o) DT - V_o (1-D) T = 0$$

$$V_o = DV_s$$

Date: / /

As $0 \leq D \leq 1$
So this is a step down converter.

$$\frac{T}{C} T_{ON} + \frac{T}{C} T_{OFF} = 0$$

$$(I_L - I_0)DT + (I_L - I_0)(1-D)T = 0$$

$$I_L = I_0$$

$\Delta I_L \rightarrow$ Ripple in inductor current = ?

During ON $V_L = V_s - V_0$

$$L \frac{di_L}{dt} = V_s - V_0$$

$$\Rightarrow L \frac{\Delta I_L}{DT} = V_s - V_0$$

$$V_0 = DV_s$$

$$\Rightarrow \Delta I_L = \frac{D(1-D)V_s}{fL}$$

$$I_{Lmax} = I_L + \frac{\Delta I_L}{2} = I_0 + \frac{\Delta I_L}{2}$$

As $I_L = I_0$

$$I_{Lmin} = I_L - \frac{\Delta I_L}{2} = I_0 - \frac{\Delta I_L}{2}$$

Source current.

Always put i/p power equal to o/p power

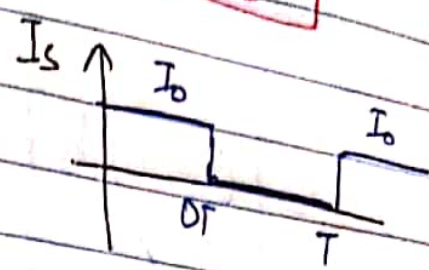
$$P_{in} = P_{out}$$

$$V_s I_s = V_o I_o$$

$$I_s = \frac{V_o I_o}{V_s}$$

switch current $I_{sw} = I_s$

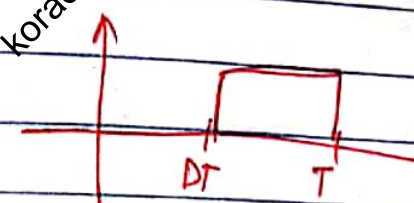
$$I_{sw} (avg) = I_o \frac{DT}{T}$$



$$I_{sw} (avg) = I_o D = D I_{Lavg}$$

$$I_s_{rms} = I_{sw_{rms}} = I_o \sqrt{\frac{DT}{T}} = \sqrt{D} I_o$$

Diode current



$$I_D (avg) = I_o \frac{(1-D)T}{T} = (1-D) I_o$$

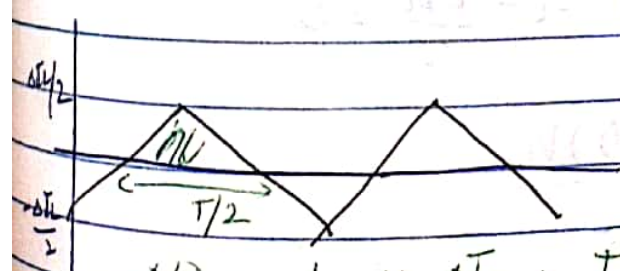
ΔV_c or $\Delta V_o = ?$

$$I_c = I_L - I_o$$

$$Q = CV$$

$$\Delta Q = C \Delta V$$

$$\Delta V = \frac{\Delta Q}{C}$$



$$\Delta Q = \frac{1}{2} \times \Delta I_L \times \frac{T}{2} = \frac{\Delta I_L T}{4}$$

$$\Delta V_c = \frac{D(1-D)I_o}{4C}$$

For what value of D (duty cycle) ripple in capacitor voltage is maximum.
 low inductor current.

$$\frac{d\Delta V_c}{dD} = 0$$

$$\frac{8f^2LC[(1-2D)V_s] - D(1-D)V_s \times 0}{(8f^2LC)^2} = 0$$

$$1 - 2D = 0 \Rightarrow D = \frac{1}{2} = 0.5$$

$$\Delta V_{c \text{ min}} \Big|_{D=0.5} = \frac{V_s}{2f^2LC}$$

$$\Delta I_{L \text{ min}} \Big|_{D=0.5} = \frac{V_s}{4fL}$$

Critical Inductance

Minimum value of inductor for which inductor current is just continuous.

$$I_{L \text{ min}} \approx 0$$

$$I_L - \frac{\Delta I_L}{2} = 0$$

→ R load

$$\frac{V_o}{R} = I_D = \frac{D(1-D)V_s}{2fL}$$

$$L_c = \frac{R(1-D)}{2f}$$

Critical capacitance

min value of capacitance for which op works is just continuous.

$$\Delta V_C_{min} \approx 0$$

$$V_C - \frac{\Delta V_C}{2} = 0 \Rightarrow V_0 - \frac{\Delta V_C}{2} = 0$$

$$C_C = \frac{(1-D)}{16 f^2 L}$$

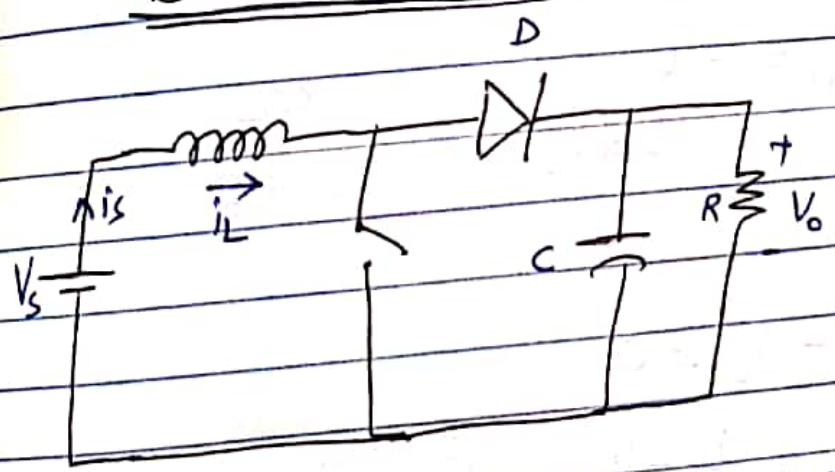
$$\Delta V_S = \frac{1}{2} \frac{D(1-D)V_S}{8 f^2 LC}$$

A for R load

$$L_C = \frac{R(1-D)}{8 f}$$

$$\Rightarrow C_C = \frac{1}{8 f R}$$

Boost Converter

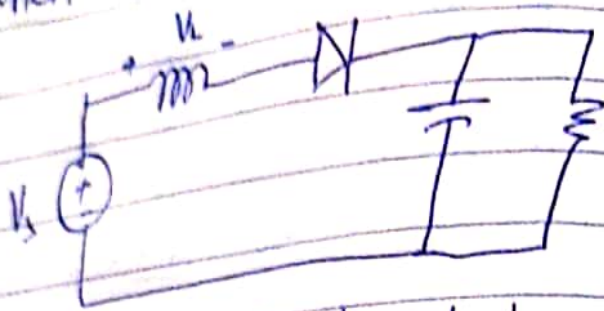


When switch is closed \rightarrow short circuit \rightarrow source has no effect on load



\rightarrow Inductor is charging
 \rightarrow current will increase linearly.

When switch is opened;



since voltage and inductive energy will get dissipated across the load.

↳ will deliver power to the load

diode is short circuited ←

we can adjust I_{Lmax} and switching frequency.

When switch is ON.

$$-V_s + V_L = 0$$

$$V_{L(on)} = V_s$$

$$I_{C(on)} = -I_o$$

$$\rightarrow AS + I_C + I_o = 0$$

When switch is open.

$$-V_s + V_{L(off)} + V_o = 0$$

$$V_{L(off)} = V_s - V_o$$

$$I_{C(off)} = I_L - I_o$$

Volt second balance

$$V_s D T + (V_s - V_o) (1-D) T = 0$$

$$V_s D T + V_s (1-D) T - V_o (1-D) T = 0$$

$$V_o(1-D) = V_s$$

$$V_o = \frac{V_s}{1-D}$$

$$0 \leq D \leq 1$$

$\hookrightarrow V_o > V_s \rightarrow$ step up chopper
 $\hookrightarrow \infty$

Ampere second balance

$$-I_o D T + (I_L - I_o)(1-D)T = 0$$

$$-I_o D T + I_L(1-D)T - I_o(1-D)T = 0$$

$$I_L = I_o$$

Ripple in inductor current, ΔI_L .

$$V_L = L \frac{di_{L,av}}{dt_{av}} = V_s$$

$$\Delta I_L = \frac{DV_s}{fL}$$

$$I_{L,max} = I_L + \frac{\Delta I_L}{2}$$

$$\hookrightarrow \frac{I_o}{1-D} + \frac{DV_s}{fL}$$

$$I_{L,min} = I_L - \frac{\Delta I_L}{2}$$

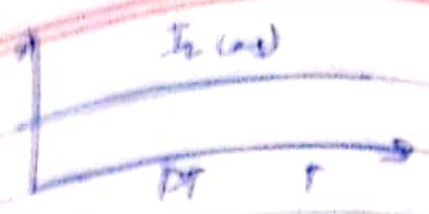
Same current

$$P_{in} = P_{out}$$

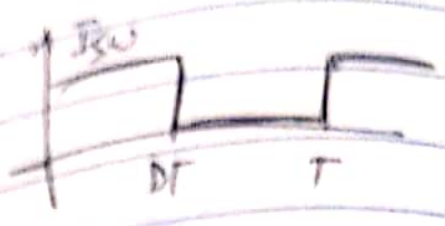
$$V_s I_s = V_o I_o$$

$$I_s = \frac{V_o I_o}{V_s}$$

Switch current



$$I_{avg} = \frac{T}{T} \left(\frac{DT}{T} \right) I_0$$



$$I_{avg} = D I_{avg} = D \frac{I_0}{1-D}$$

$$I_{rms} = \sqrt{D} I_{avg} = \sqrt{D} \frac{I_0}{1-D}$$

Diode current

$$I_{D(avg)} = \frac{1}{2} \frac{(1-D)T}{T} = \frac{1}{2} (1-D) I_0$$

$$\frac{I_0}{1-D} (1-D) \quad I_{avg} = I_0$$

$$I_{D(rms)} = I_0 \sqrt{\frac{(1-D)T}{T}} = \sqrt{(1-D)} I_0$$

Ripple in o/p voltage $\Delta V_c = \Delta V_o$

During ON.

Capacitor will deliver power to the load.

$$I_c = -I_0 \quad V_{min} \quad DT$$

$$C \frac{dV_c}{dt} = -I_0 \quad \int dV = \int_0^{DT} -\frac{I_0}{C} dt$$

$$V_{min} - V_{max} = -\frac{I_0}{C} DT$$

$$\Delta V_C = V_{\max} - V_{\min}$$

$$\Delta V_C = \frac{I_0 DT}{C}$$

$$\Delta V_C = \frac{DI_0}{fC}$$

Critical inductance.

$$I_{L\min} = 0$$

$$I_L - \frac{\Delta I_L}{2} = 0$$

$$\frac{I_0}{1-D} = \frac{1}{2} \left(\frac{DV_s}{fL_c} \right) = \frac{V_0}{R(1-D)}$$

$$L_c = \frac{D(1-D)^2 R}{2f}$$

$$= \frac{V_s}{(1-D)R(1-D)}$$

Critical capacitance

$$V_{C\min} = 0$$

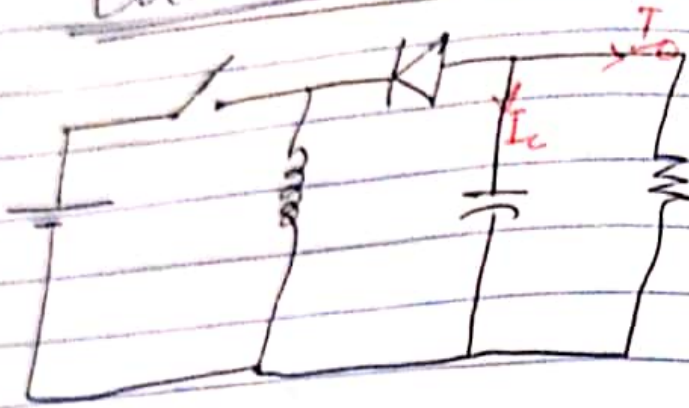
$$V_C - \frac{\Delta V_C}{2} = 0$$

$$V_0 = \frac{1}{2} \left(\frac{I_0 D}{fC} \right) = \frac{DV_0}{2RfC}$$

$$C_c = \frac{D}{2fR}$$

4 to 8 same in converters.

Buck Boost Converter



When switch is closed at $t=0$

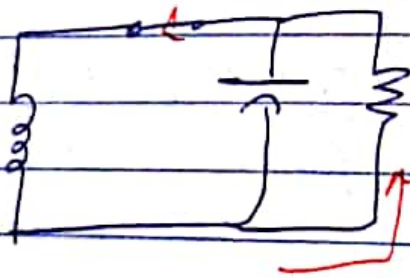
supply will charge L .
 $\rightarrow I_L$ increase till DT .



$$V_L = V_s$$

is delay \rightarrow capacitor \rightarrow capacitor
 is delay \rightarrow to load.

Switch open at $t=DT$



Inductor will deliver energy to load.

Switch ON 0 to DT

$$V_{L(on)} = V_s$$

$$I_{L(on)} = -I_o$$

Switch OFF DT to T

$$V_{L(off)} - V_o = 0$$

$$V_{L(off)} = V_o$$

$$I_{L(off)} = -(I_o + I)$$

Voltage send side,

$$V_s DT - V_o (1-D) T = 0$$

$$V_o = \frac{-D}{(1-D)} V_s$$

Current send side

$$I_o DT - (I_L + I_o) (1-D) T = 0$$

$$I_L = \frac{-I_o}{1-D}$$

$$\frac{dI_L}{dt}, \quad V_L = V_s = L \frac{di}{dt} = L \frac{d\Delta I_L}{DT}$$

$$I_L = \frac{DV_s}{fL}$$

$$I_{L_{max}} = I_L + \frac{\Delta I_L}{2}$$

$$I_{L_{min}} = I_L - \frac{\Delta I_L}{2}$$

$$|I_{L_{avg}}| = \frac{I_o}{(1-D)}$$

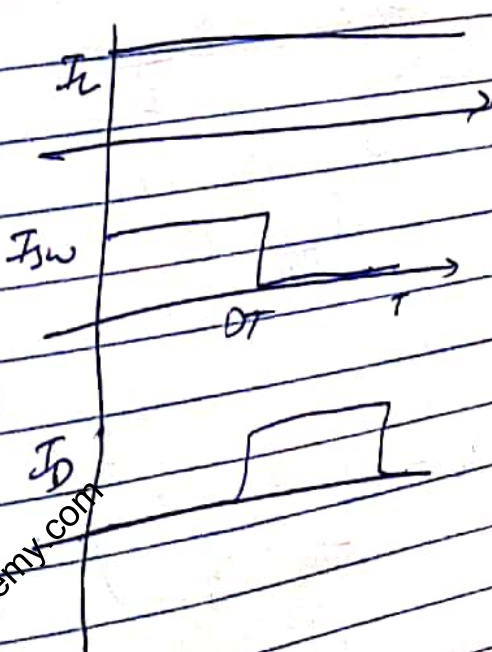
① $P_M = P_{out} \quad I_s = \frac{V_o I_o}{V_s}$

$$I_{sw (avg)} = D I_L$$

$$I_{sw rms} = \sqrt{D} I_L$$

$$I_{D (avg)} = (1-D) I_L$$

$$I_{D rms} = \sqrt{(1-D)} I_L$$



$$\frac{dV_c}{dV} = \frac{dV_c}{dV} \cdot \frac{dV}{dV} = -I_0$$

$$I_{c,av} = -I_0$$

$$C \frac{dV_c}{dt} = -I_0$$

$$\int_{V_{min}}^{V_{max}} dV_c = \int_0^T \frac{-I_0}{C} dt$$

$$dV_c = \frac{D I_0}{fC}$$

$D=1 \Rightarrow dV_c$ & maxin
↳ ripple η .

Central inductance

$$I_{c,av} = 0 \quad \frac{I_c}{2} = 0$$

$$\frac{dV_s}{R(1-D)^2} = \frac{-V_0}{R(1-D)} = \frac{-I_0}{(1-D)} = \frac{1}{2} \left(\frac{dV_c}{fL_c} \right)$$

$$L_c = \frac{R(1-D)^2}{2f}$$

Central capacitance

$$V_{c,min} = 0 \quad V_c - \frac{dV_c}{2} = 0$$

$$V_0 = \frac{dV_c}{2}$$

$$V_0 = \frac{1}{2} \left(\frac{D I_0}{fC} \right) = \frac{1}{2} \left(\frac{D V_0}{fCR} \right)$$

$$C_c = \frac{1}{fR}$$